

Lifting weak lensing degeneracies with a field-based likelihood

Natalia Porqueres

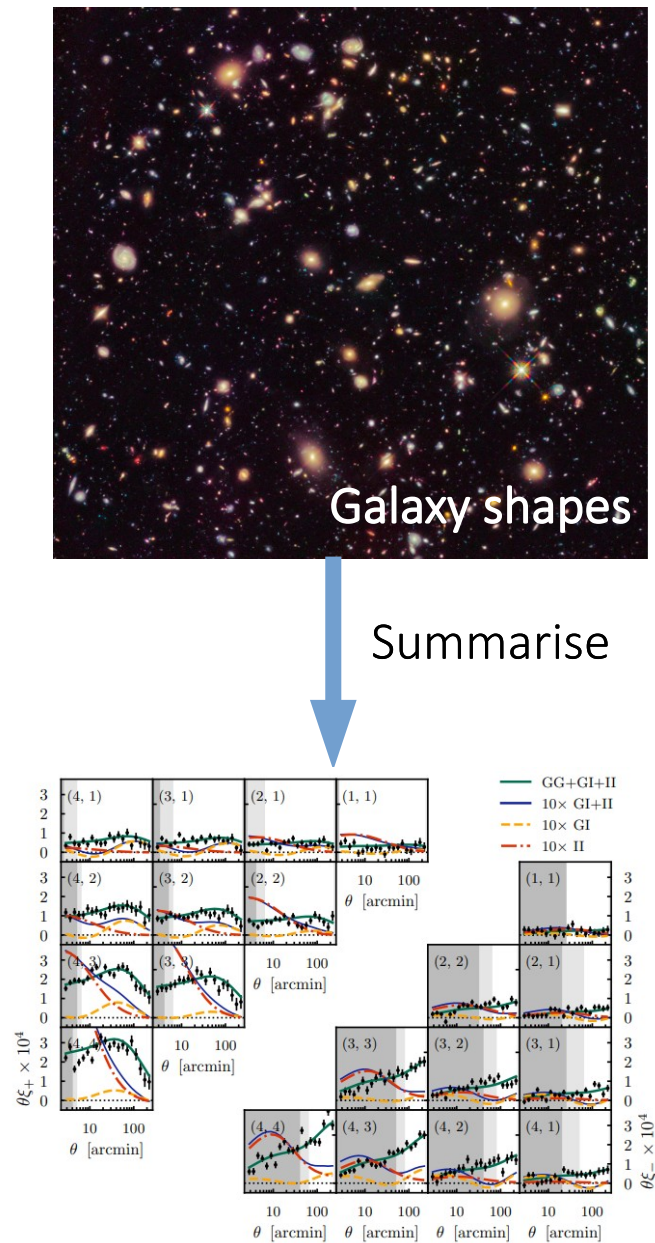
with Alan Heavens, Daniel Mortlock, Guilhem Lavaux, Lucas Makinen

LSS Prague – 28/6/2023

The standard approach to shear analysis



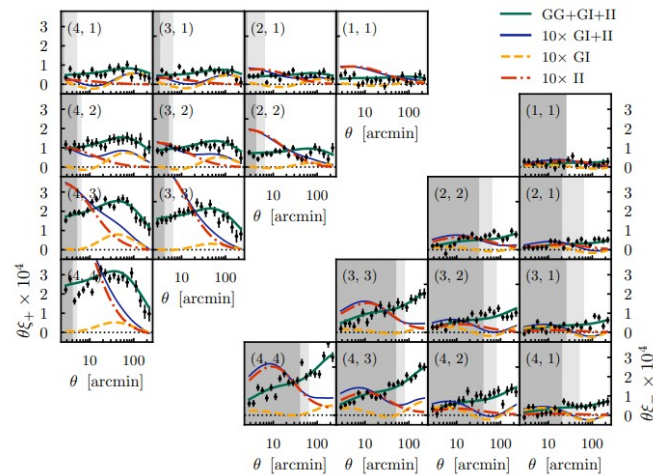
The standard approach to shear analysis



The standard approach to shear analysis



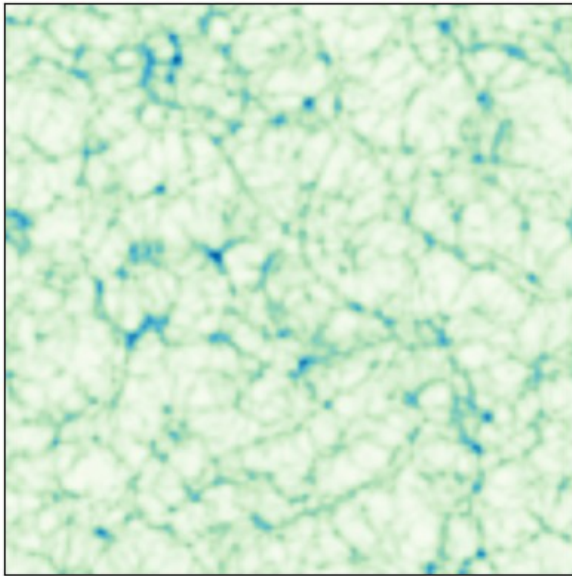
Summarise



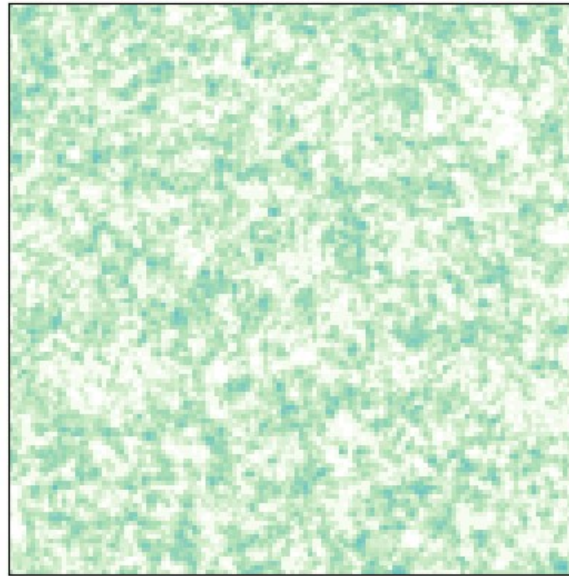
Does this capture all the information?

Is the standard approach enough?

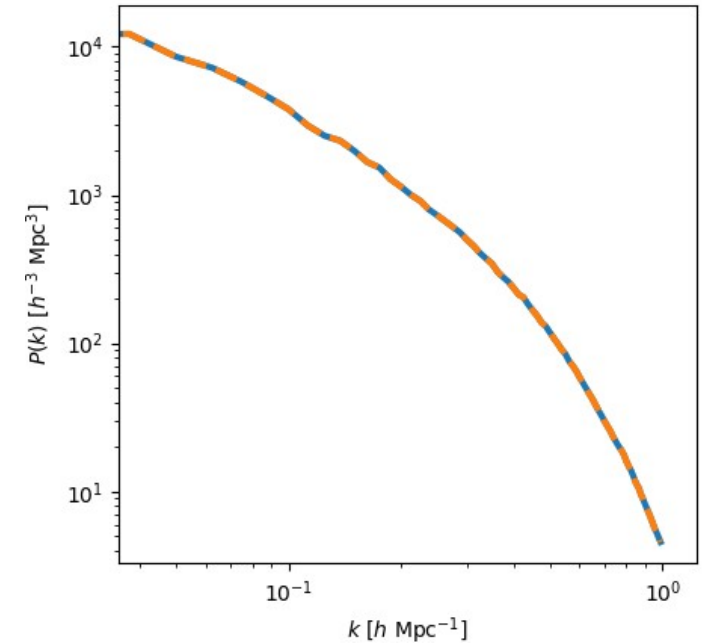
The standard approach misses information!



Cosmic web

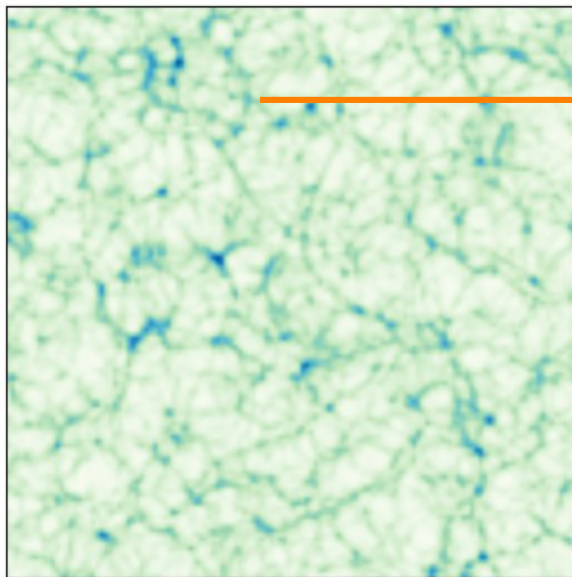


Gaussian random field

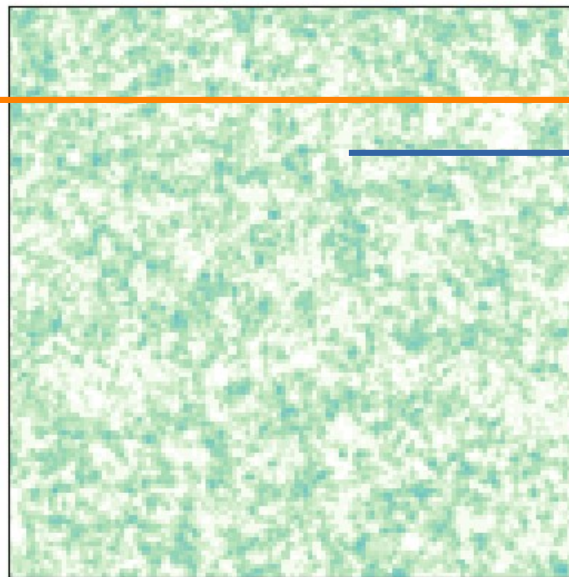


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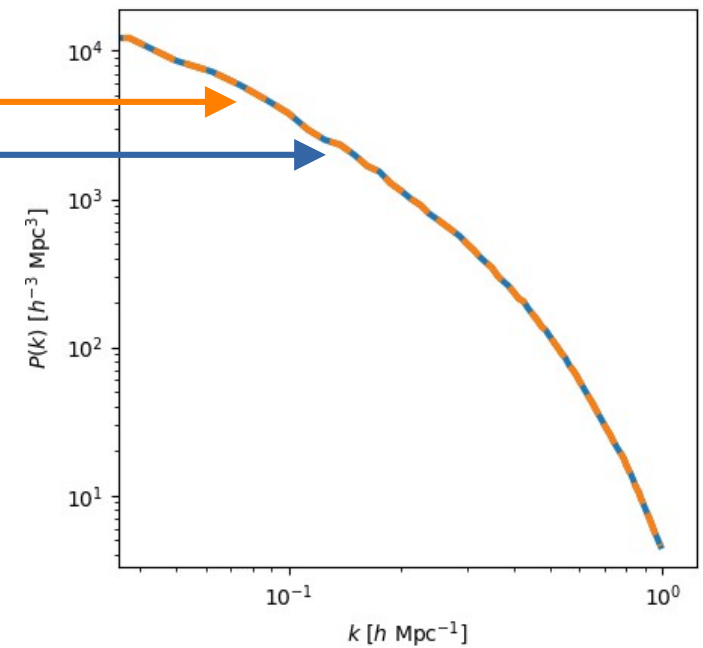
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Cosmic web

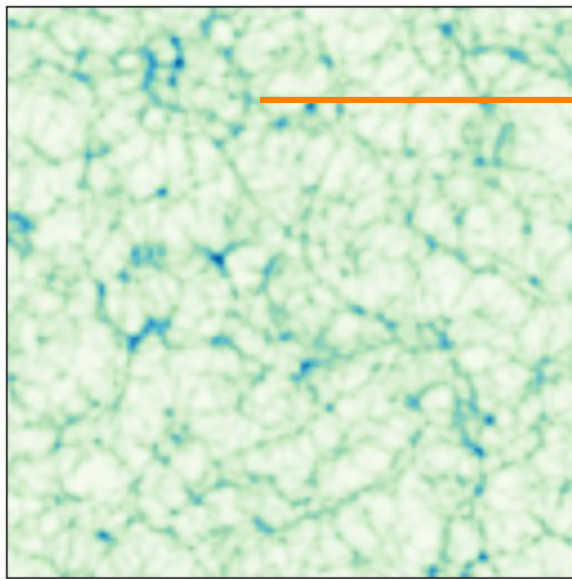


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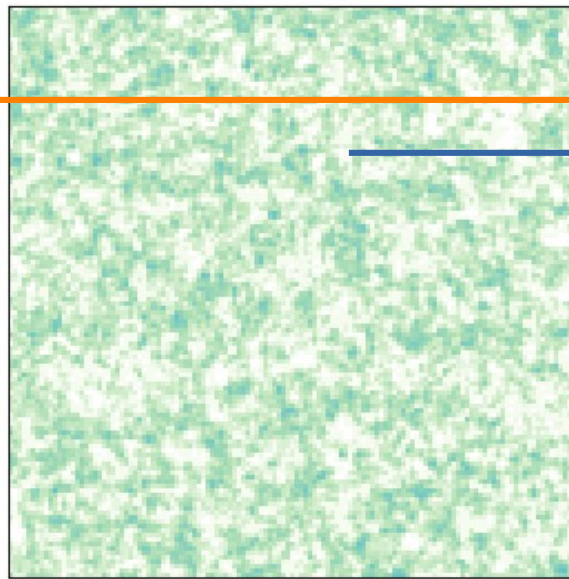


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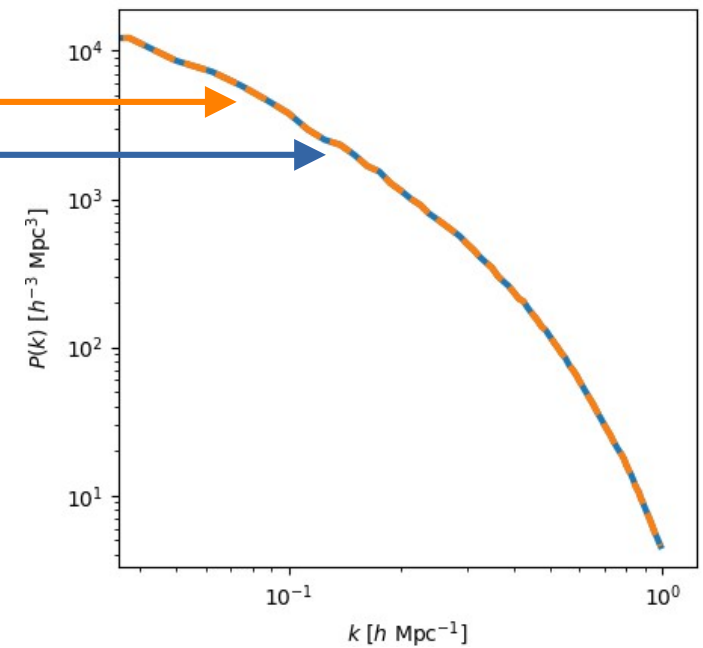
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Cosmic web



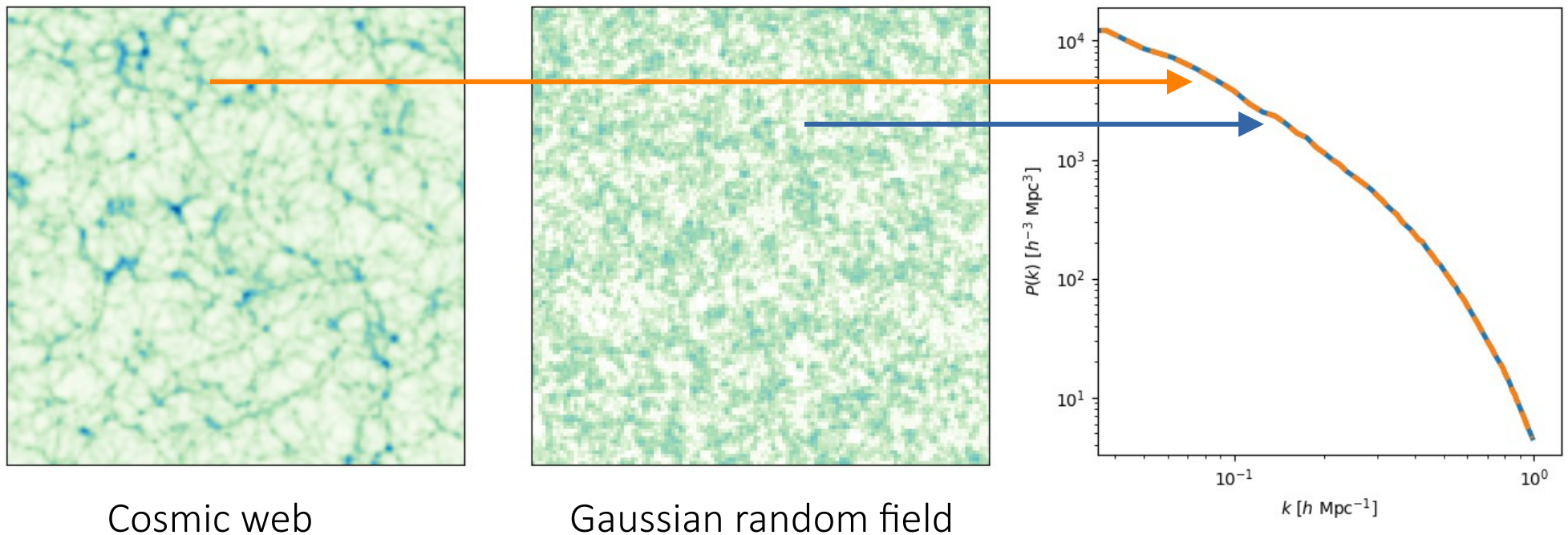
Gaussian random field



- Higher-order statistics: what are the sampling distributions? And covariance matrix?

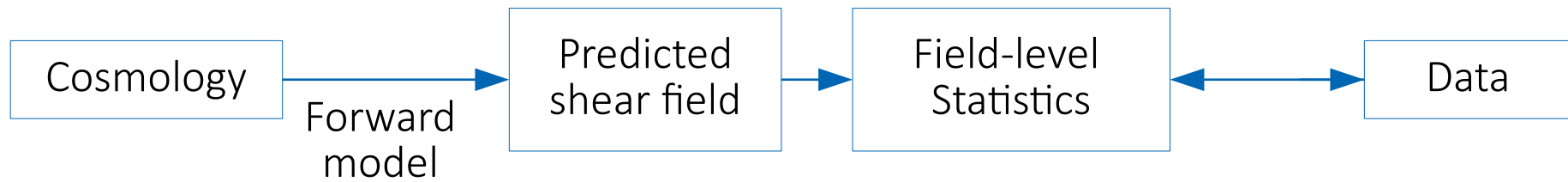
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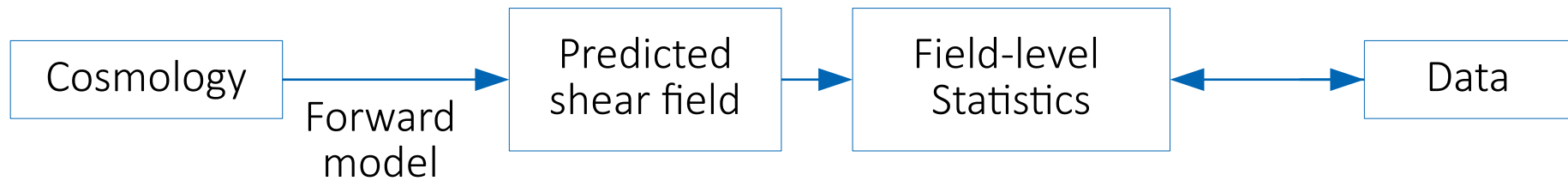


- Higher-order statistics: what are the sampling distributions? And covariance matrix?
- Field-based approach without data compression of the pixelised shear.

The field-level approach

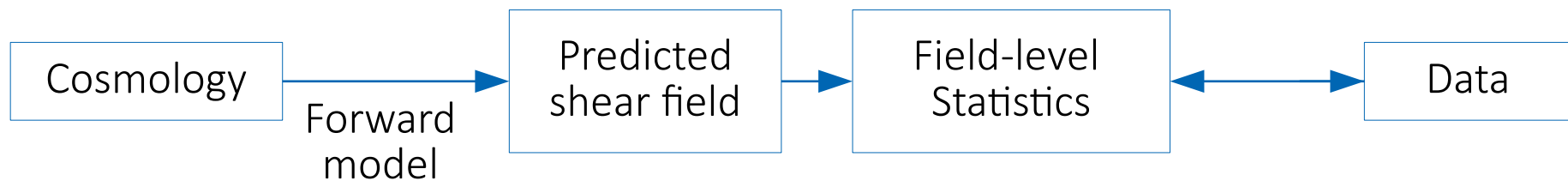


The field-level approach



Statistics pixel by pixel can access all the information

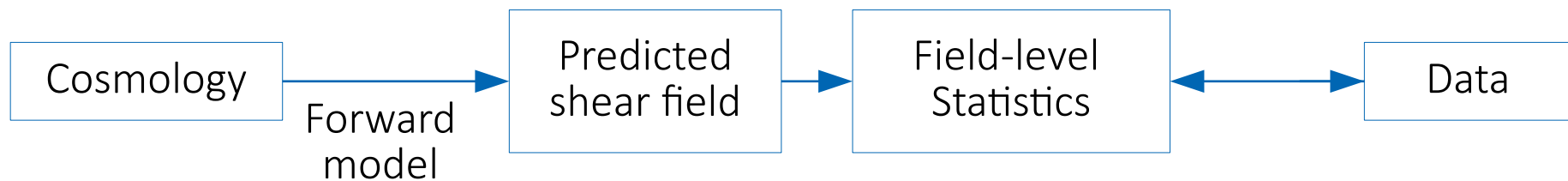
The field-level approach



Statistics pixel by pixel can access all the information

Probabilistic forward model → Simulations are constrained by the data

The field-level approach

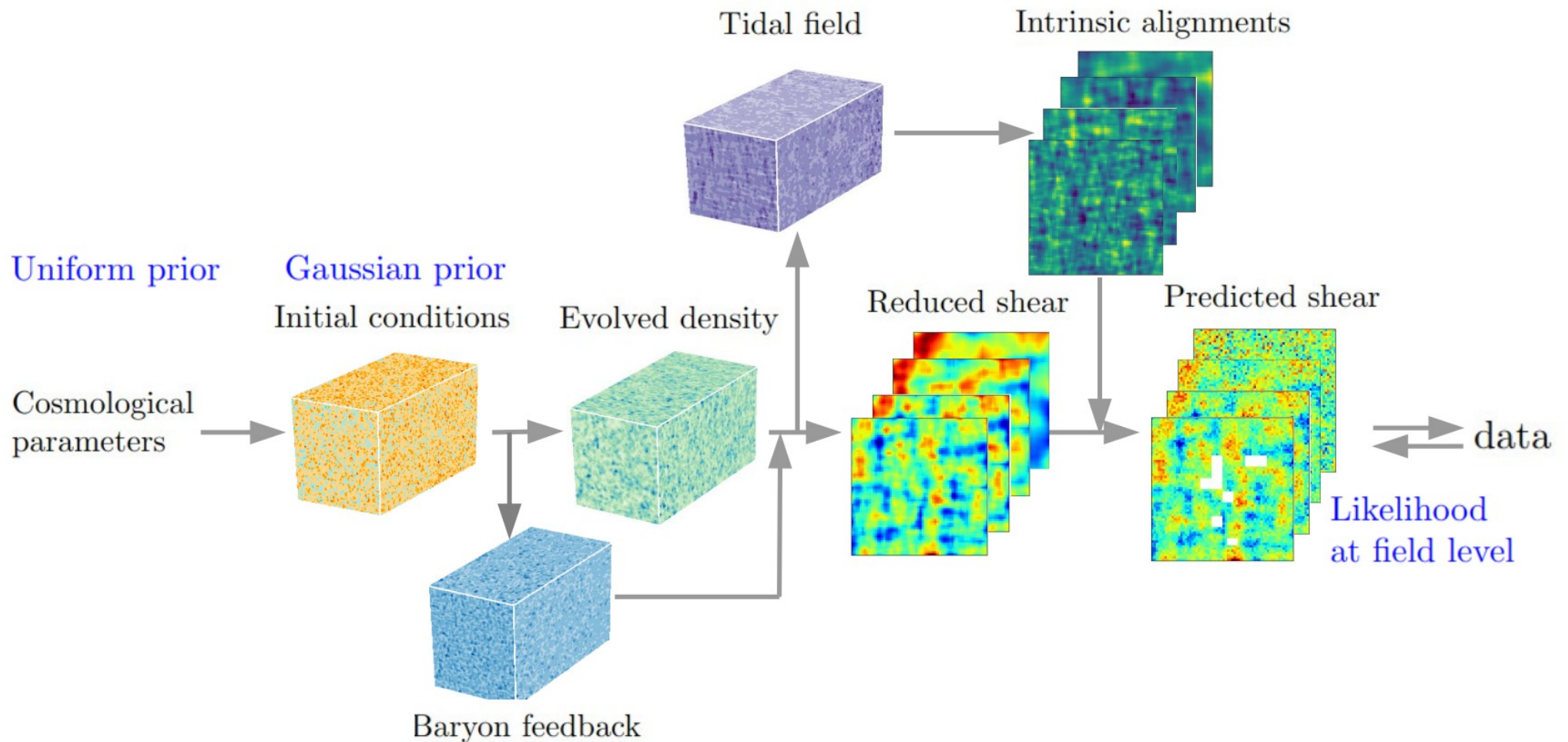


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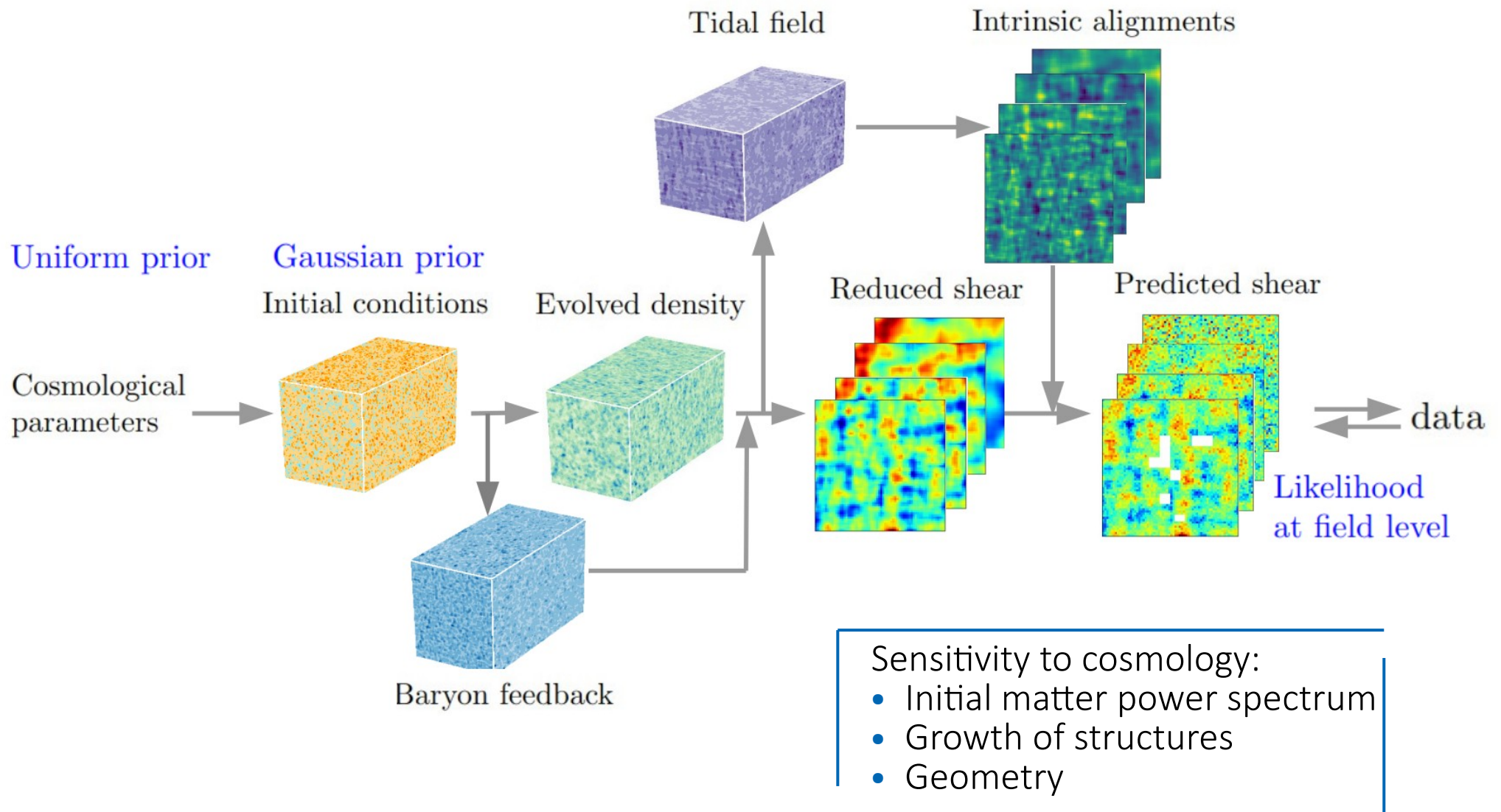
Probabilistic forward model → Simulations are constrained by the data

BORG framework: gravity model

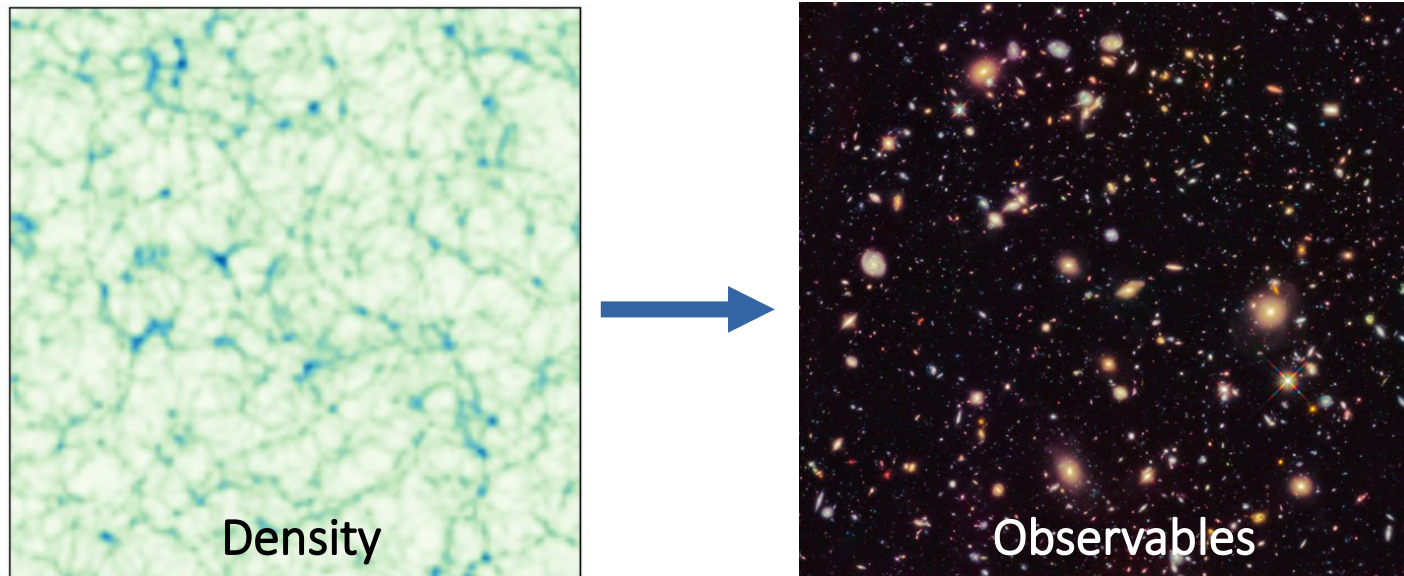
The forward model of BORG-WL



The forward model of BORG-WL



Intrinsic alignments: Tidal alignment and tidal torquing



TATT model includes linear (tidal alignment) and quadratic (tidal torque) terms

$$\gamma_1^{\text{IA}}(\mathbf{r}, \boldsymbol{\vartheta}) = (C_1 + C_{1\delta}\delta)(s_{xx} - s_{yy}) + C_2(s_{xk}s_{xk} - s_{yk}s_{yk})$$

$$\gamma_2^{\text{IA}}(\mathbf{r}, \boldsymbol{\vartheta}) = 2(C_1 + C_{1\delta}\delta)s_{xy} + 2C_2s_{xk}s_{yk},$$

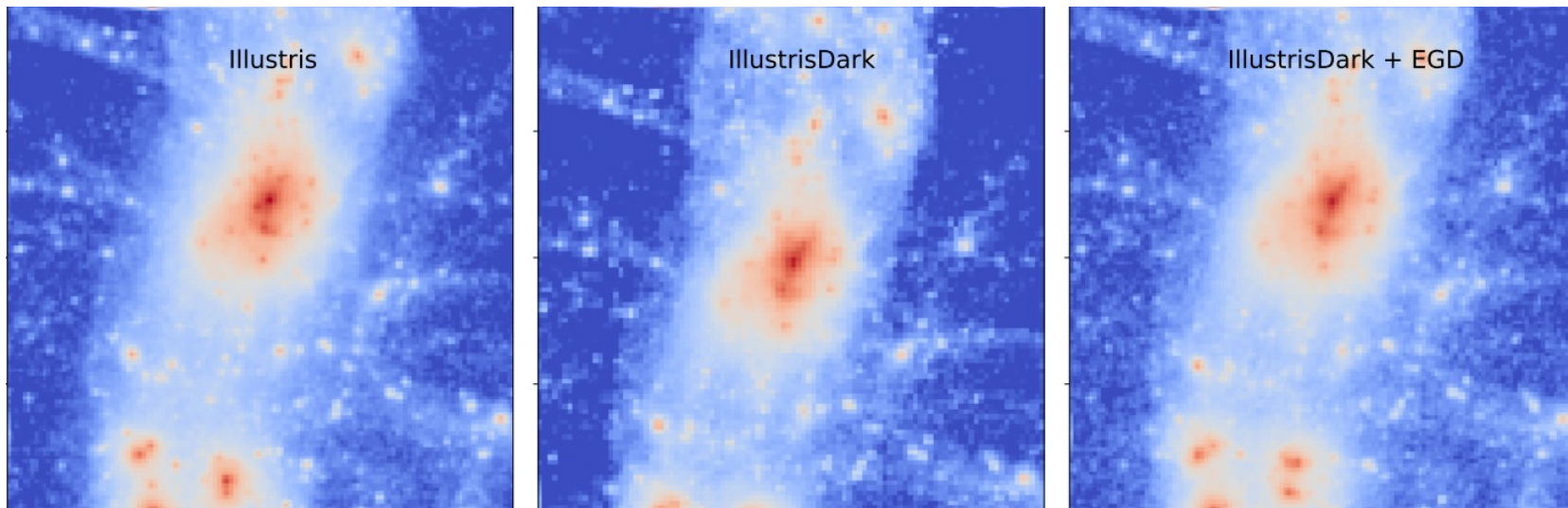
Blazek+ 2017

Baryon feedback: Enthalpy gradient descent model

Displaces dark matter particles with

$$\mathbf{S}_{\text{baryons}} = -\frac{\beta}{H_0^2} \frac{k_B T_0}{\mu} \frac{\gamma}{\gamma - 1} \nabla [\mathbf{O}_J(1 + \delta)]^{\gamma-1}$$

Assumes power law equation of state of baryons $T(\delta) = T_0(1 + \delta_b)^{\gamma-1}$



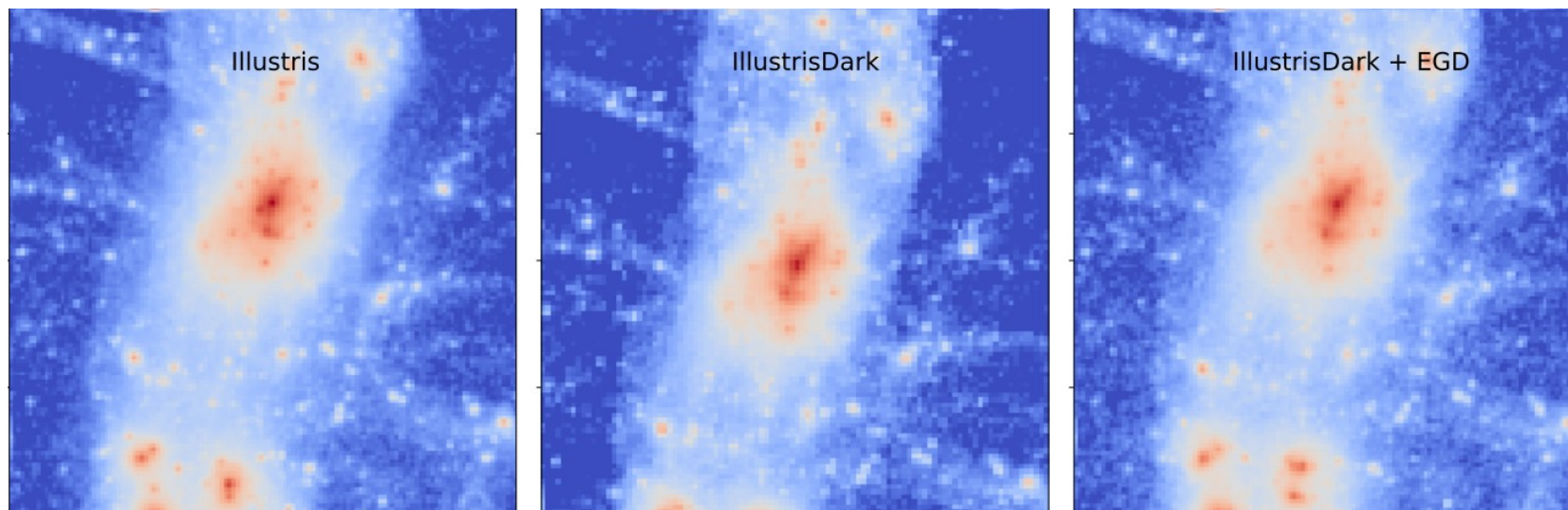
Dai & Seljak, 2018

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Dai & Seljak, 2018

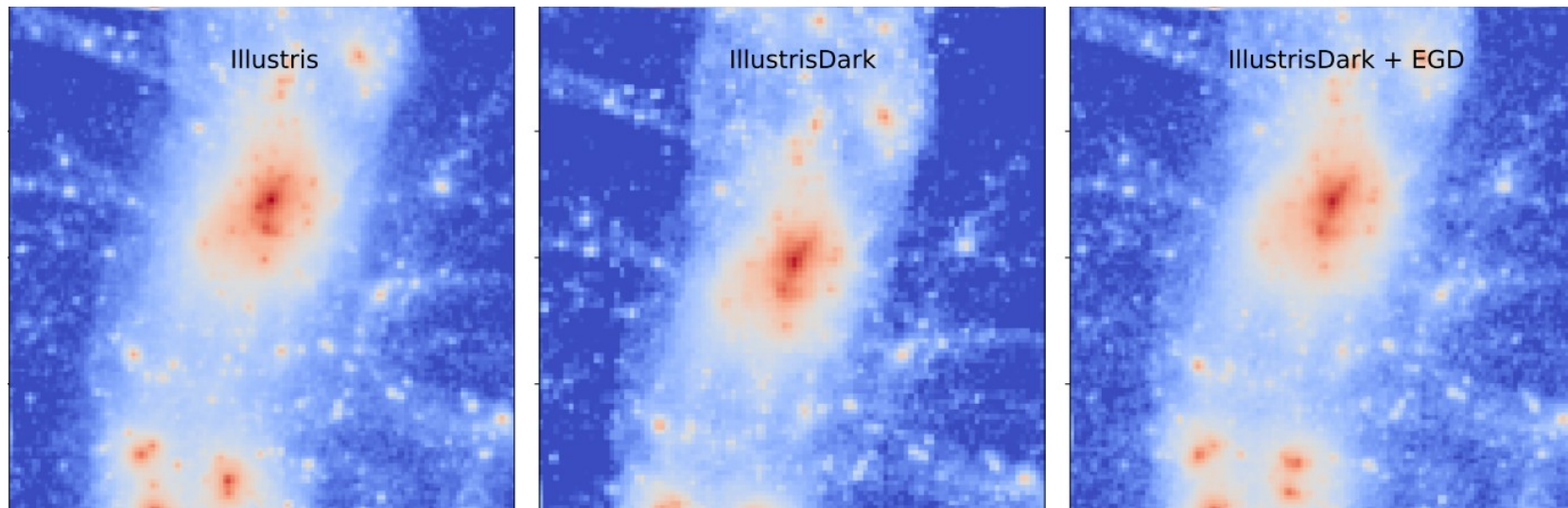
- Self calibration of model parameters.

Baryon feedback: Enthalpy gradient descent model

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Dai & Seljak, 2018

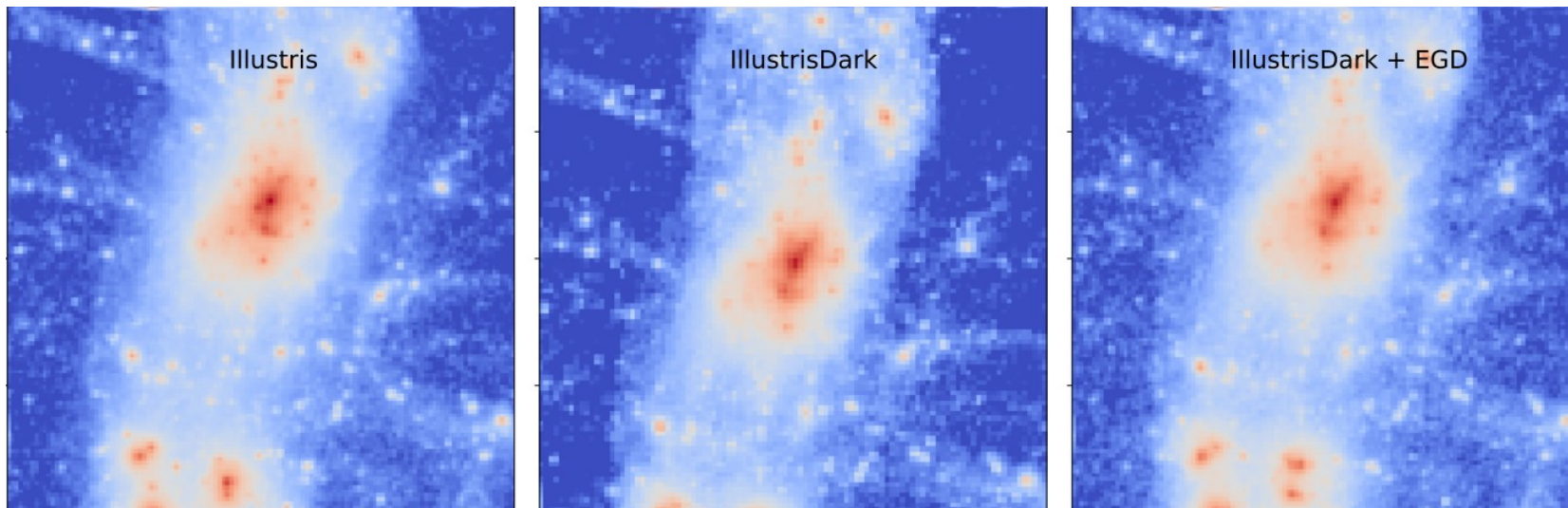
- Self calibration of model parameters.
- Displaces particles independently of whether they are in a halo.

Baryon feedback: Enthalpy gradient descent model

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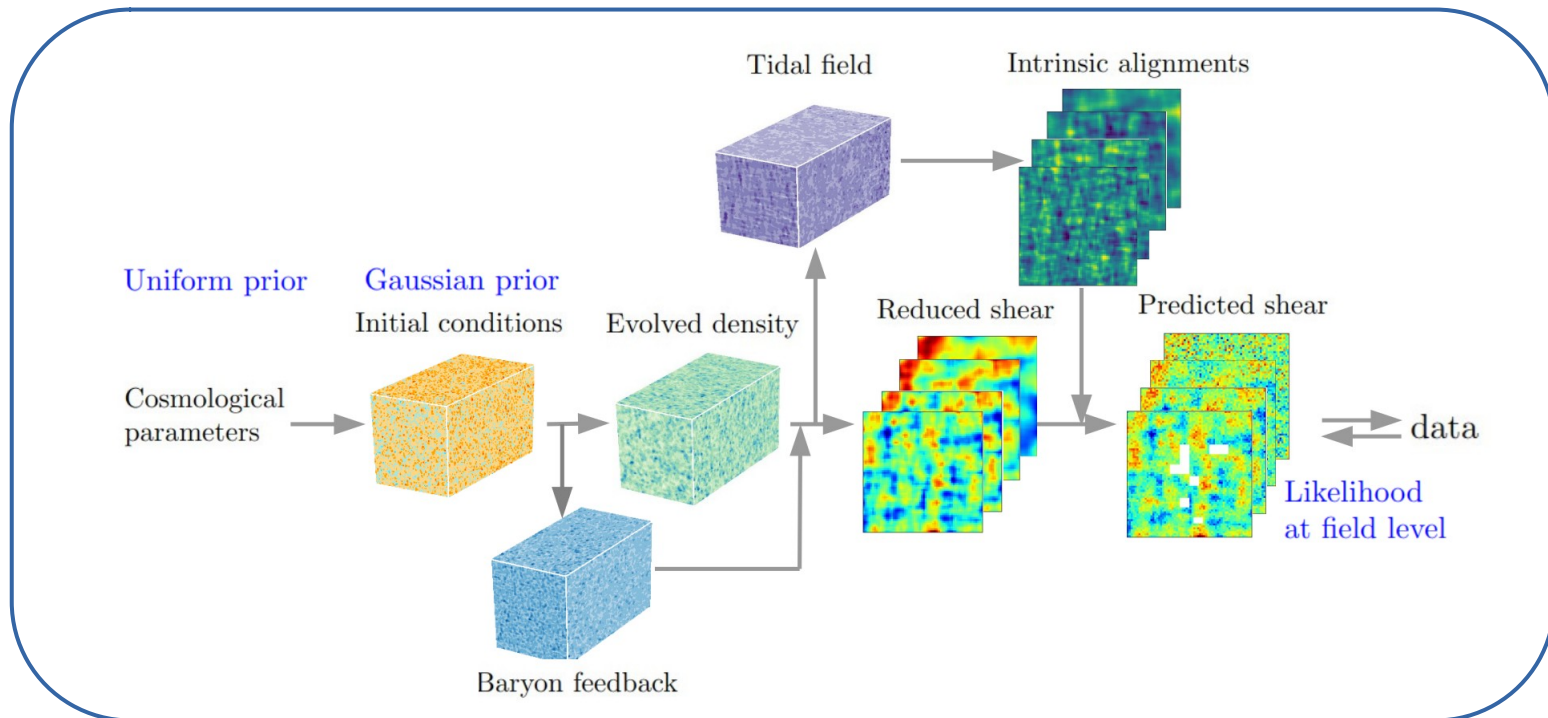
Assumes power law equation of state of baryons $T(\delta) = T_0(1 + \delta_b)^{\gamma-1}$



Dai & Seljak, 2018

- Self calibration of model parameters.
- Displaces particles independently of whether they are in a halo.
- Fully differentiable.

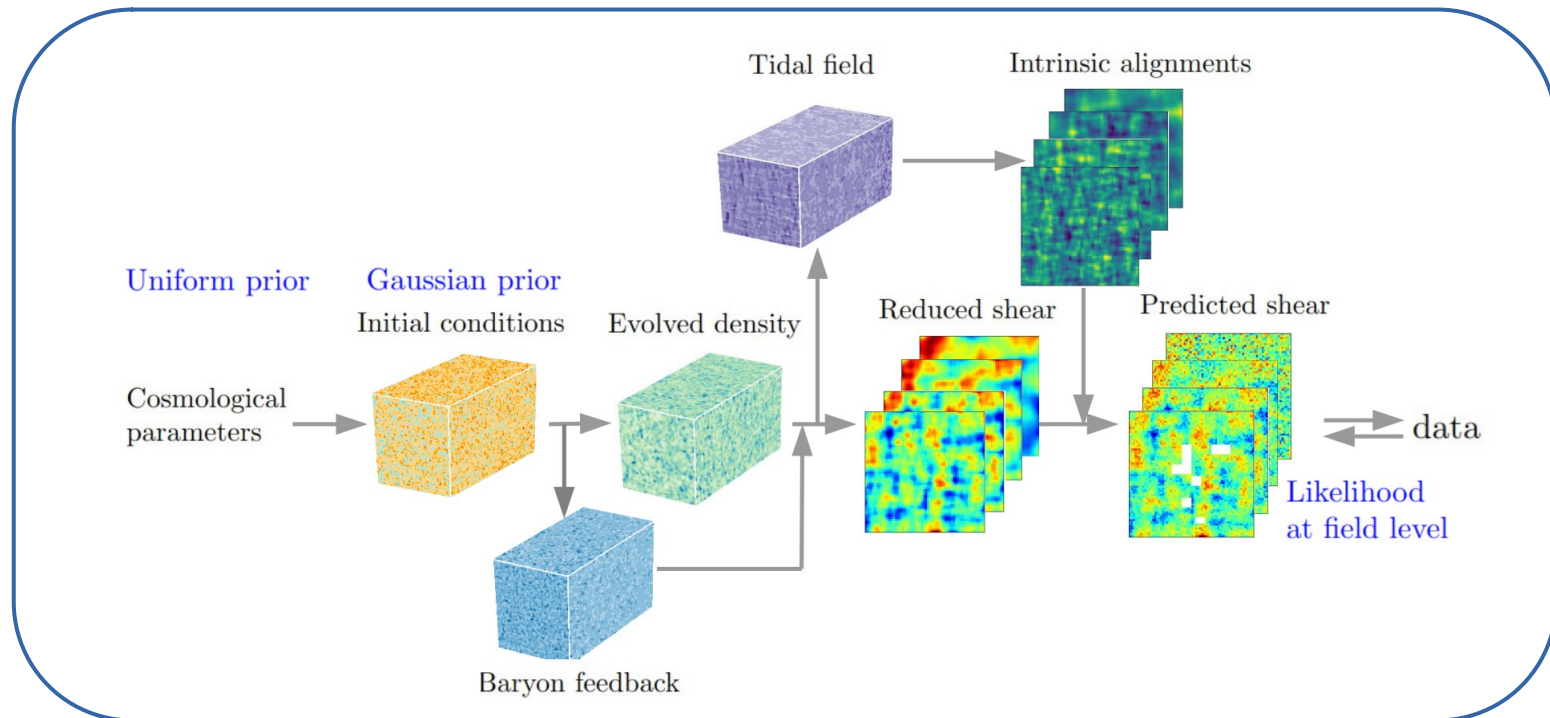
The likelihood



Likelihood: Assuming Gaussian noise in pixelised shear

$$\log \mathcal{L} = -\frac{1}{2} \sum_b \sum_{mn} \frac{(\epsilon_{1,mn}^b - \hat{\epsilon}_{1,mn}^b)^2 + (\epsilon_{2,mn}^b - \hat{\epsilon}_{2,mn}^b)^2}{\sigma_b^2}$$

The likelihood

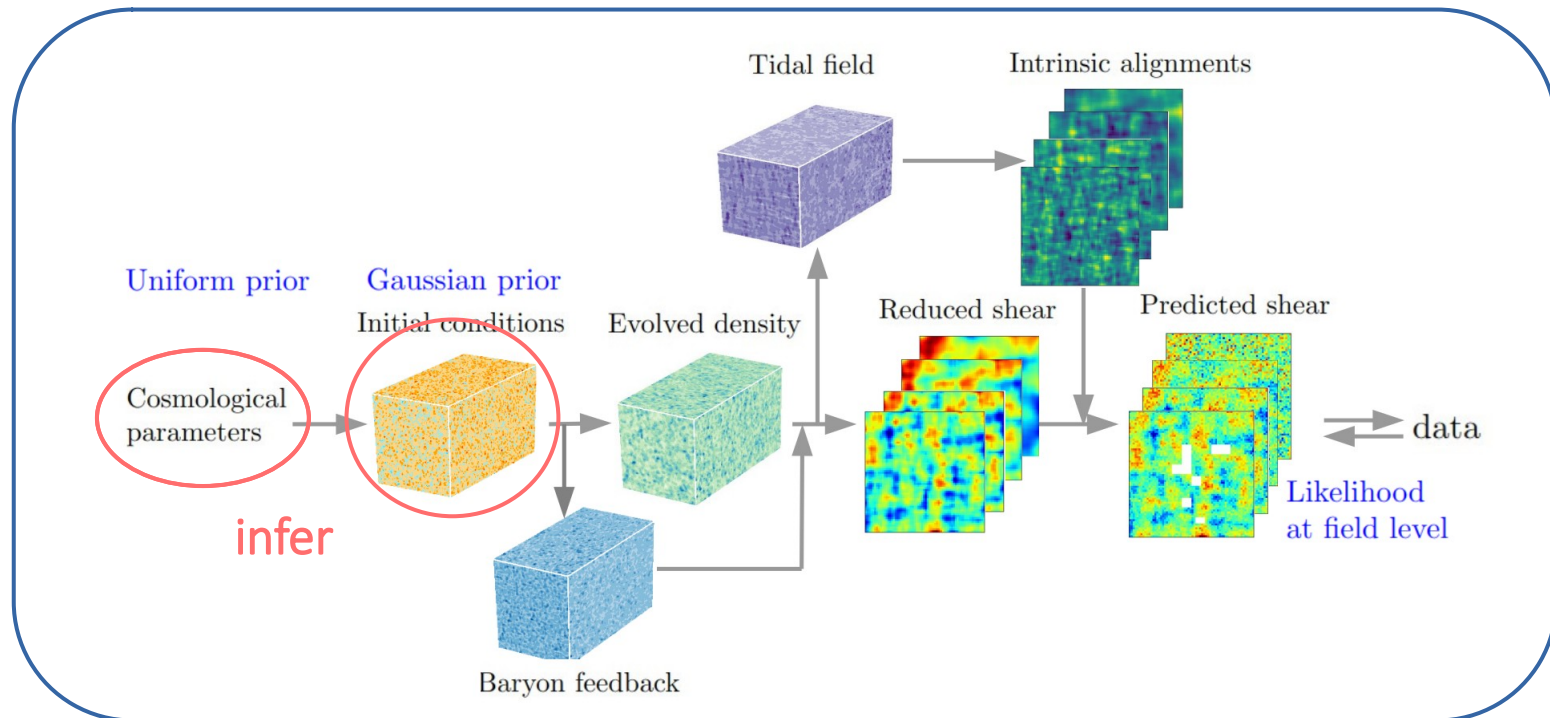


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Doesn't need covariance matrix! $\sigma_b = \sigma_\epsilon / \sqrt{N_b}$

The likelihood

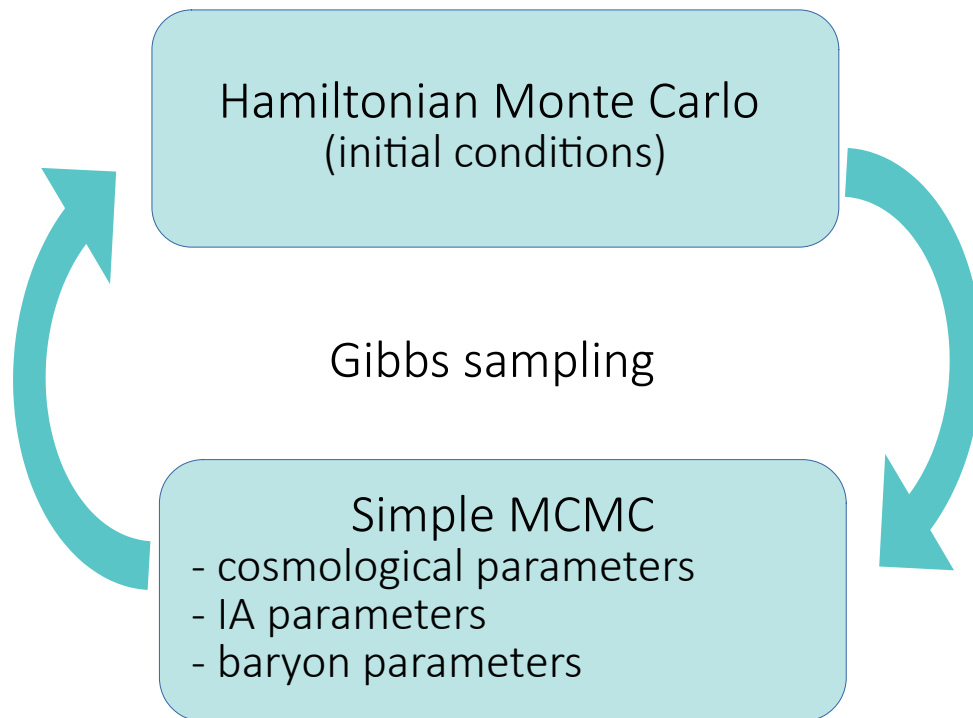


Likelihood: Assuming Gaussian noise in pixelised shear

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Doesn't need covariance matrix! $\sigma_b = \sigma_\epsilon / \sqrt{N_b}$

Sampling efficiently in a high-dimensional space



Addresses curse of dimensionality by:

- exploiting information in gradients
- using conserved quantities

The proof of concept

Results with synthetic data

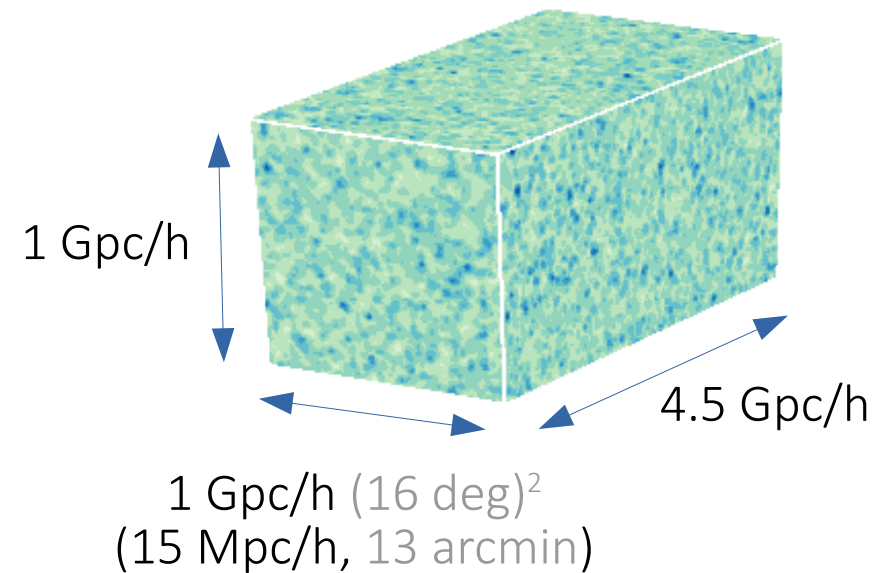
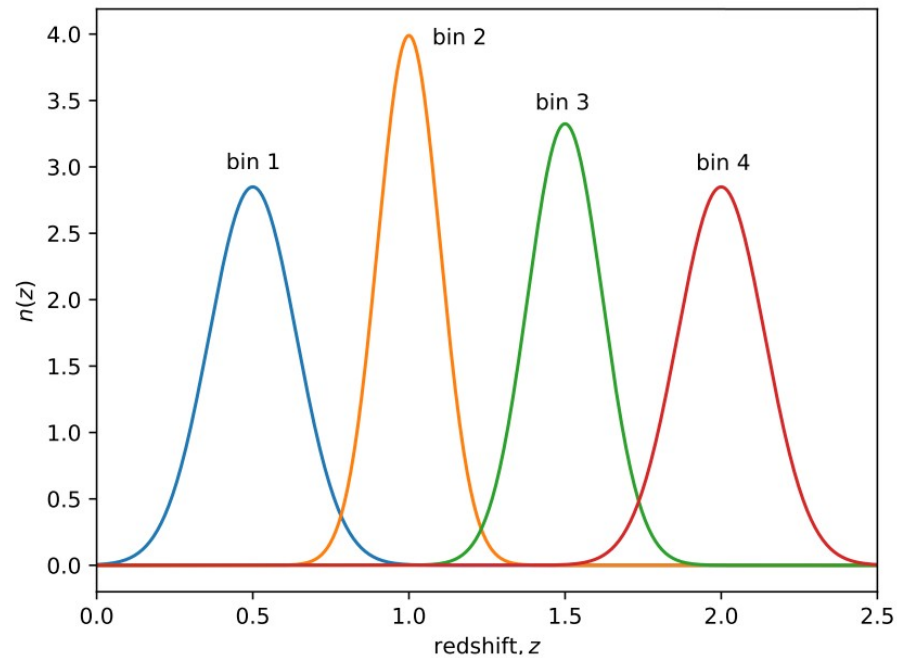
The proof of concept

Results with synthetic data

How much do we get from going to the field level?

Simulated data

Tomographic bins

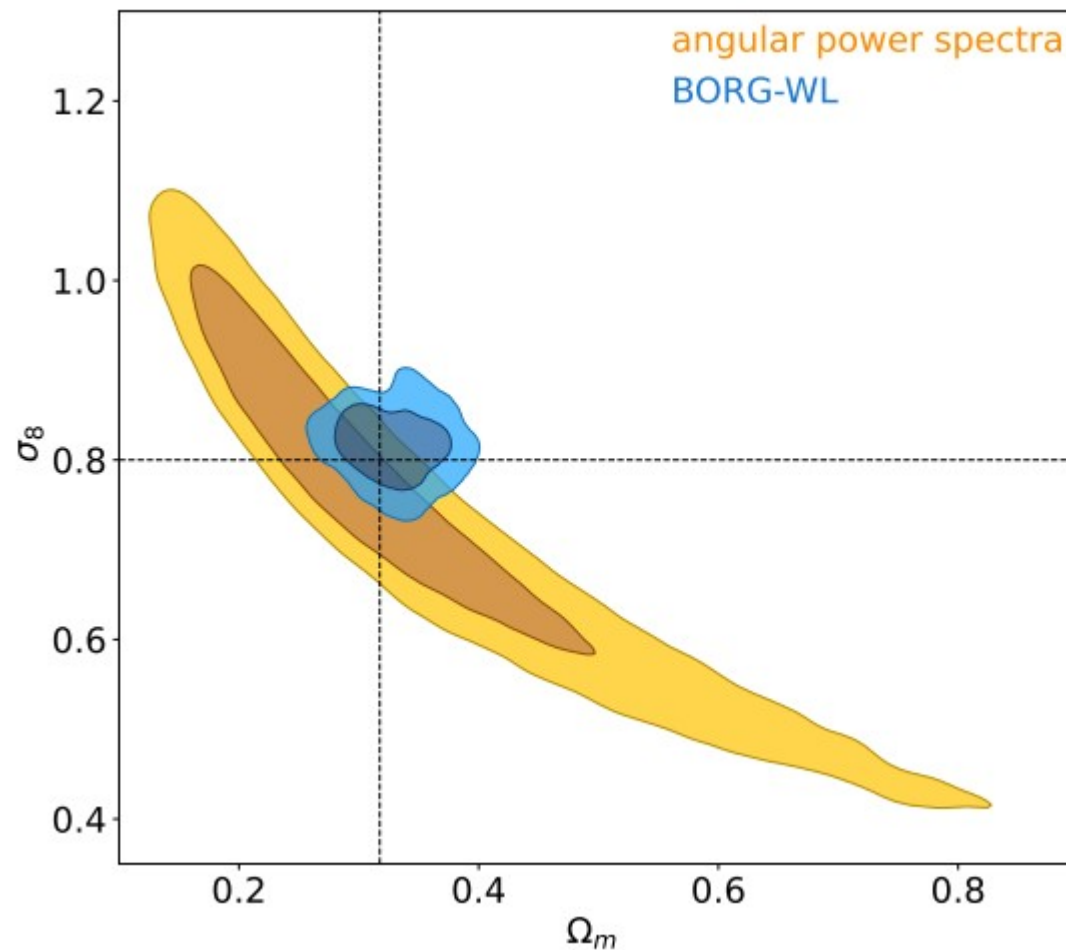


Gravity model: LPT.

Gaussian pixel-noise: 30 sources per square arcmin.

Intrinsic alignment amplitudes: DES values (0.18, 0.8, 0.1)

Comparison of cosmology constraints



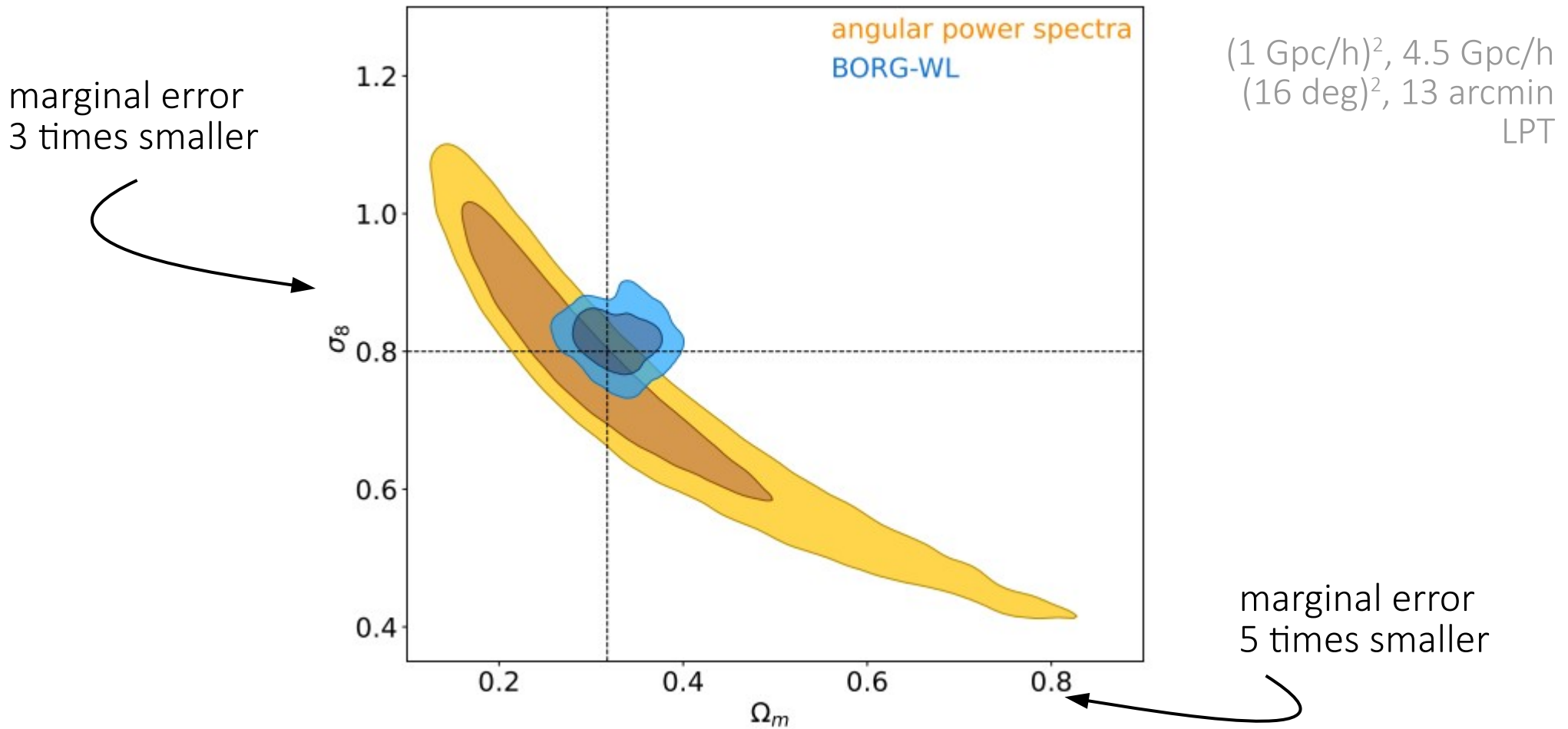
$(1 \text{ Gpc/h})^2$, 4.5 Gpc/h
 $(16 \text{ deg})^2$, 13 arcmin
LPT

Field-level approach **lifts degeneracy** by extracting more information from the data

Porqueres+2023

Natalia Porqueres

Comparison of cosmology constraints

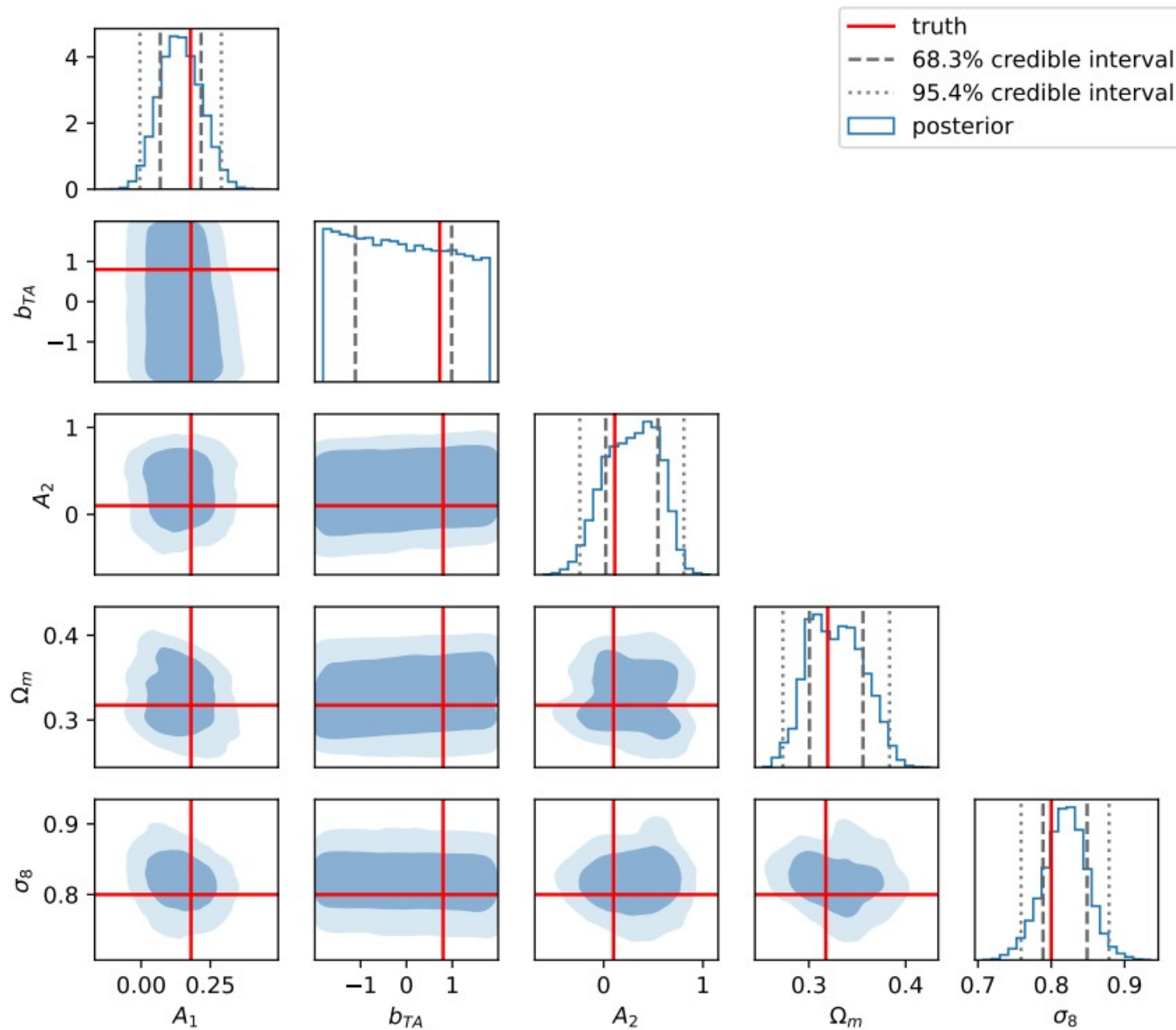


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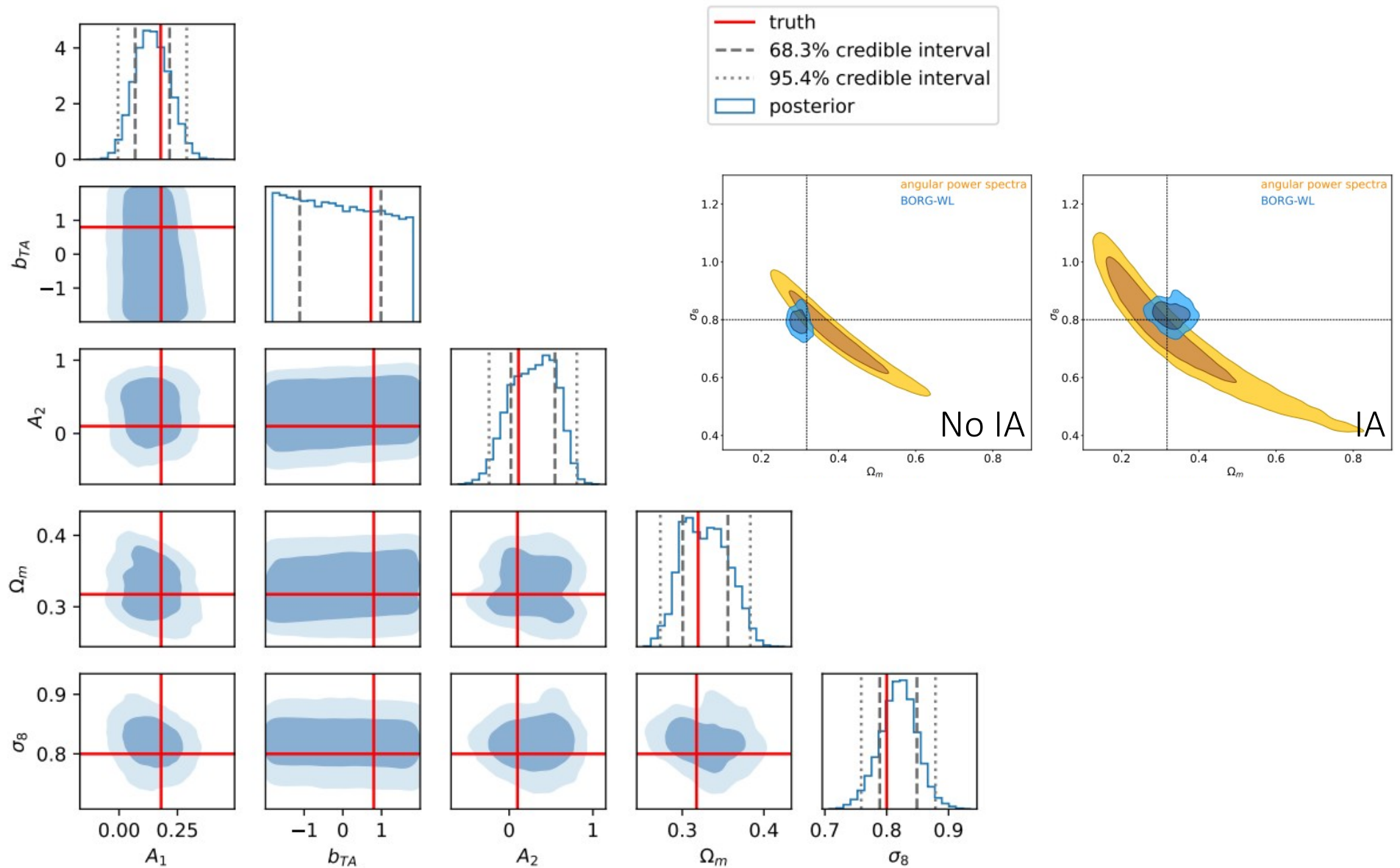
Porqueres+2023

Natalia Porqueres

Intrinsic alignment parameters

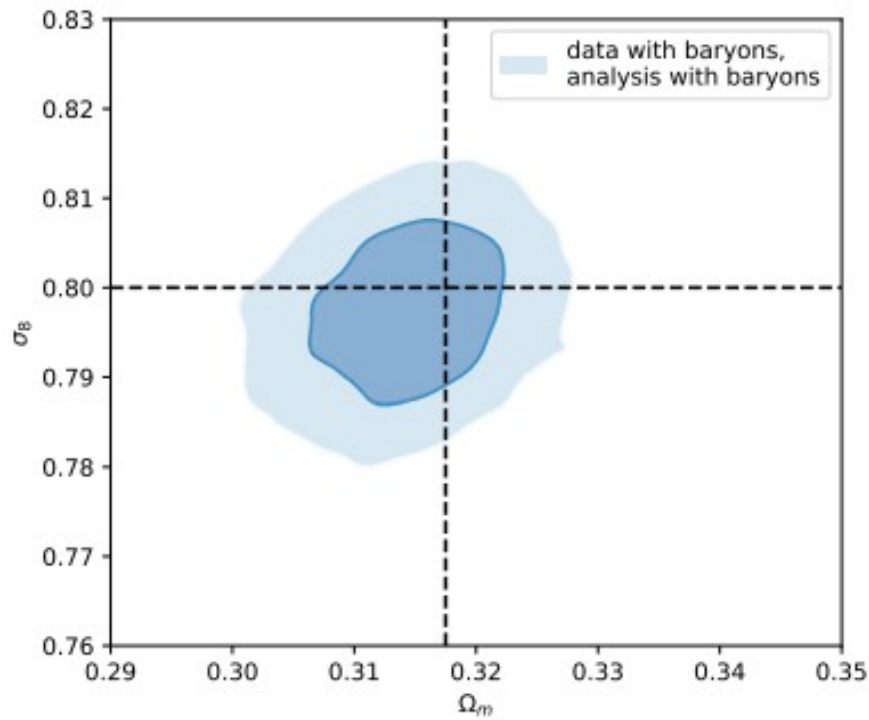


Intrinsic alignment parameters

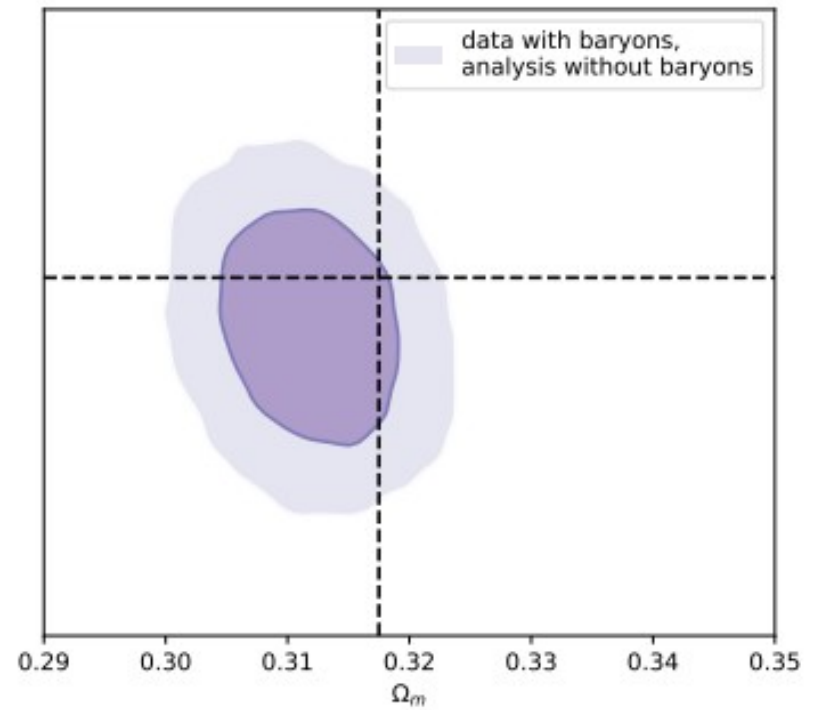


Baryon feedback parameters

$(0.1 \text{ Gpc}/h)^2, 2.5 \text{ Gpc}/h$
 $(3 \text{ deg})^2, 5 \text{ arcmin}$
LPT

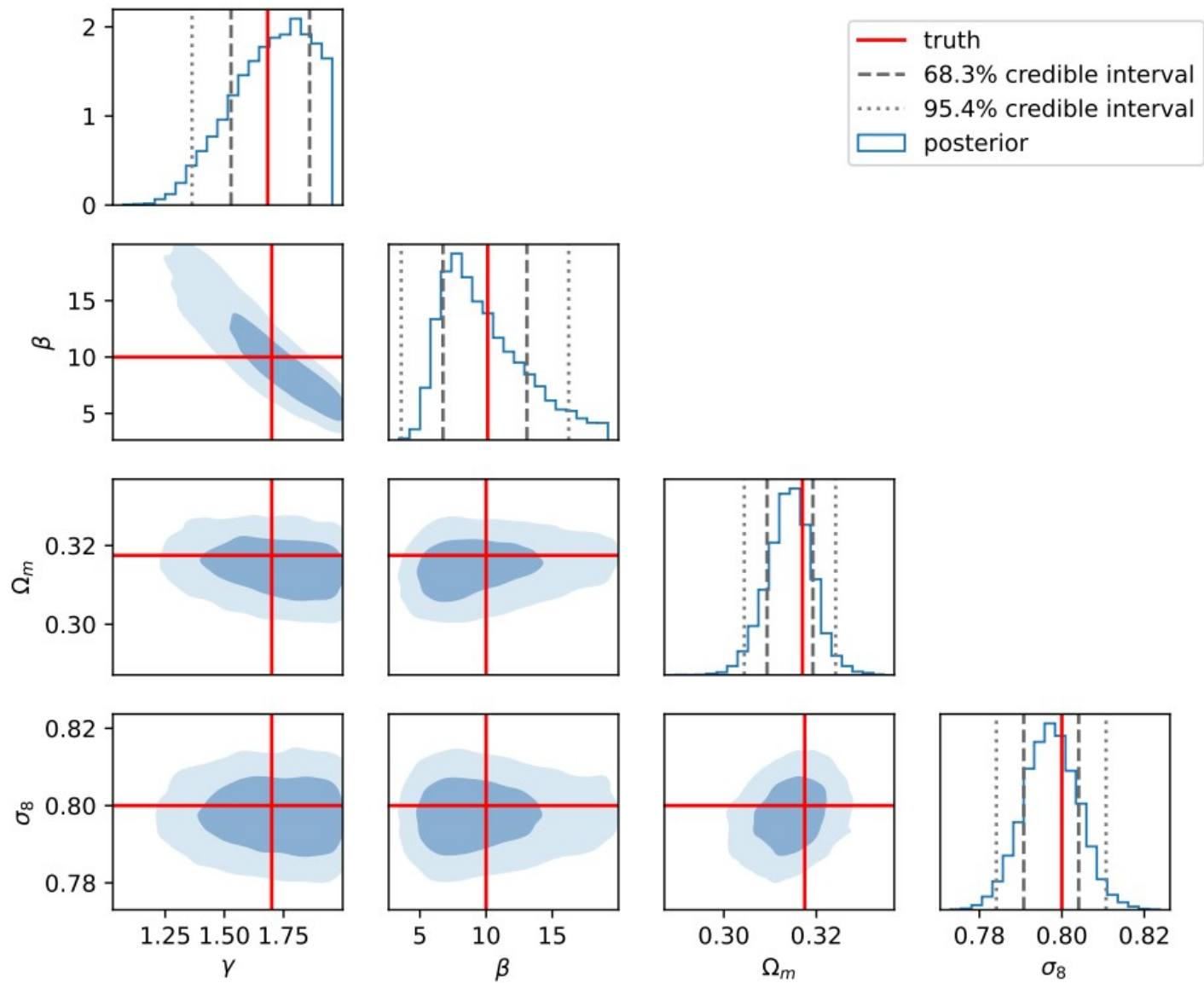


self-consistent

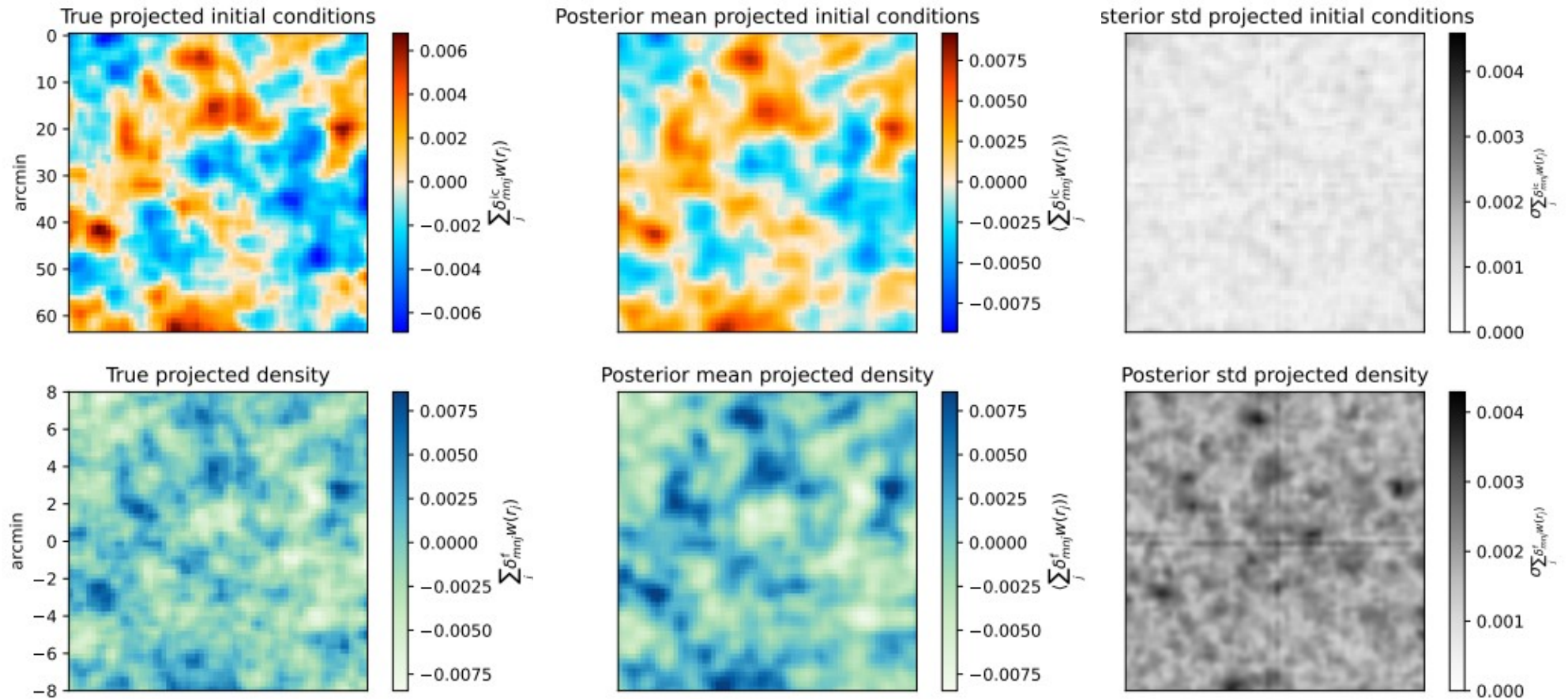


model misspecification

Posterior distribution baryon parameters

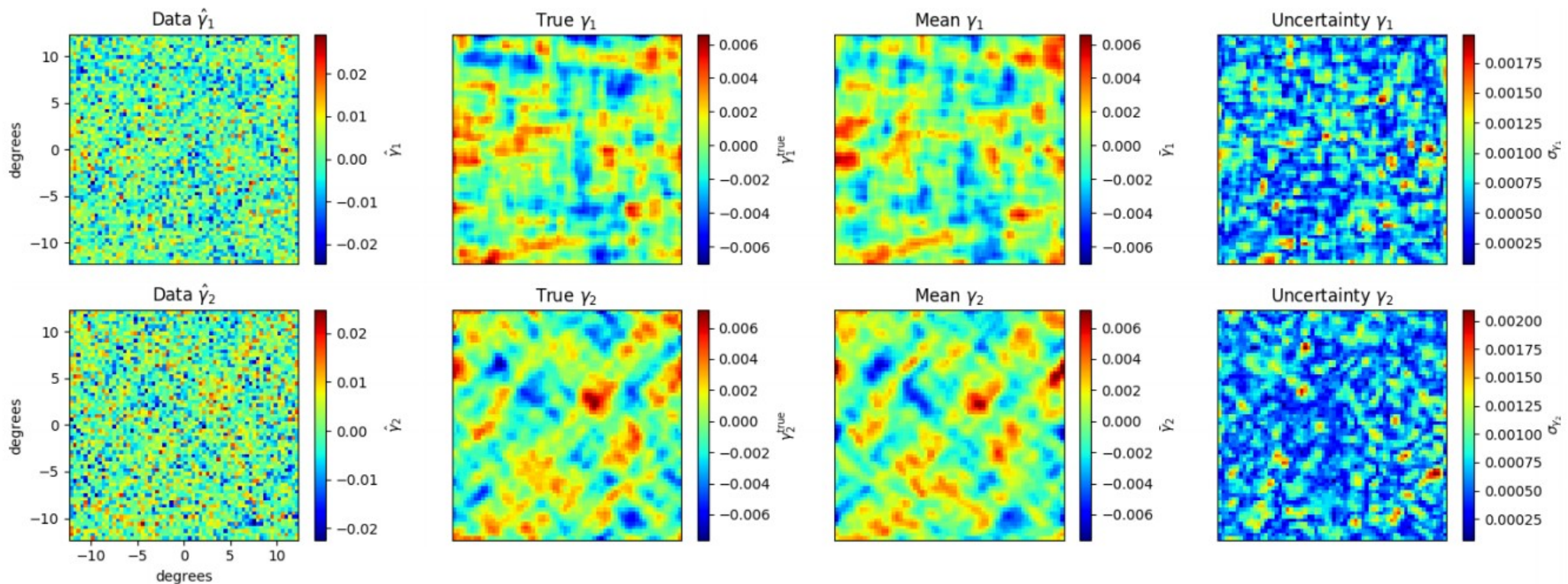


Projection of inferred density fields



How can we test the results with such high dimensionality?

Posterior predictive tests: Can the inferred quantities explain the data?



The current state of BORG

Currently supported data

Galaxy clustering
(Jasche et al 2012)

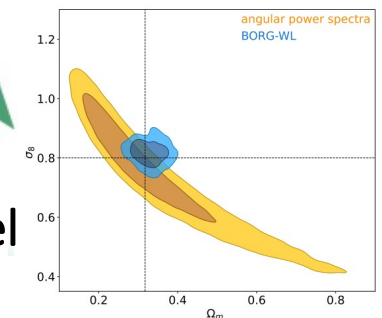
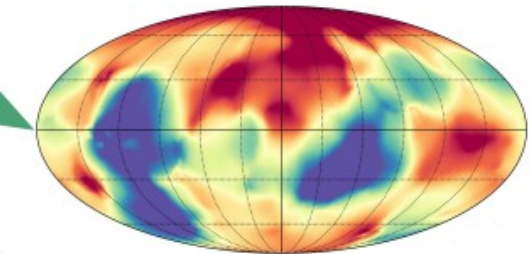
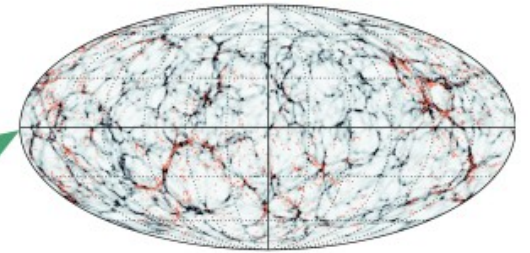
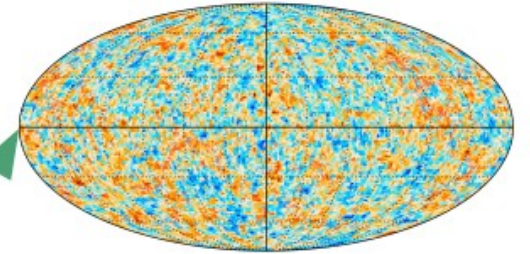
Cosmic shear
(NP et al 2021)

Velocity tracers
(Prideaux et al 2022)

Lyman- α forest
(NP et al 2019)

BORG

Generated data products



Multiple probe analysis will become possible **at field level**

The current state of BORG

Currently supported data

Real data!

Galaxy clustering
(Jasche et al 2012)

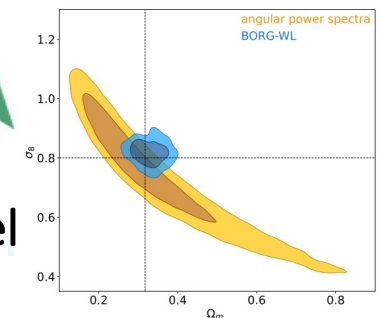
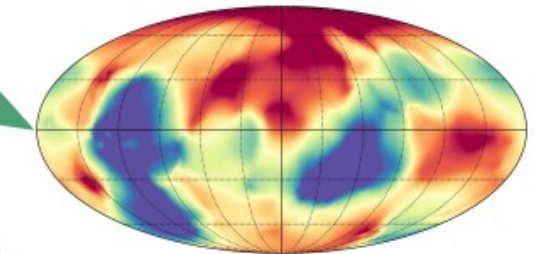
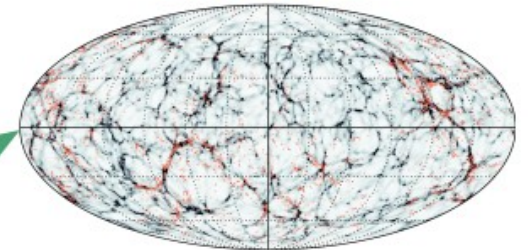
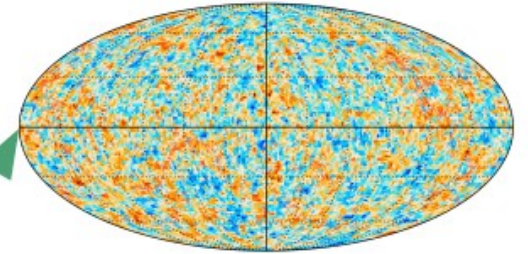
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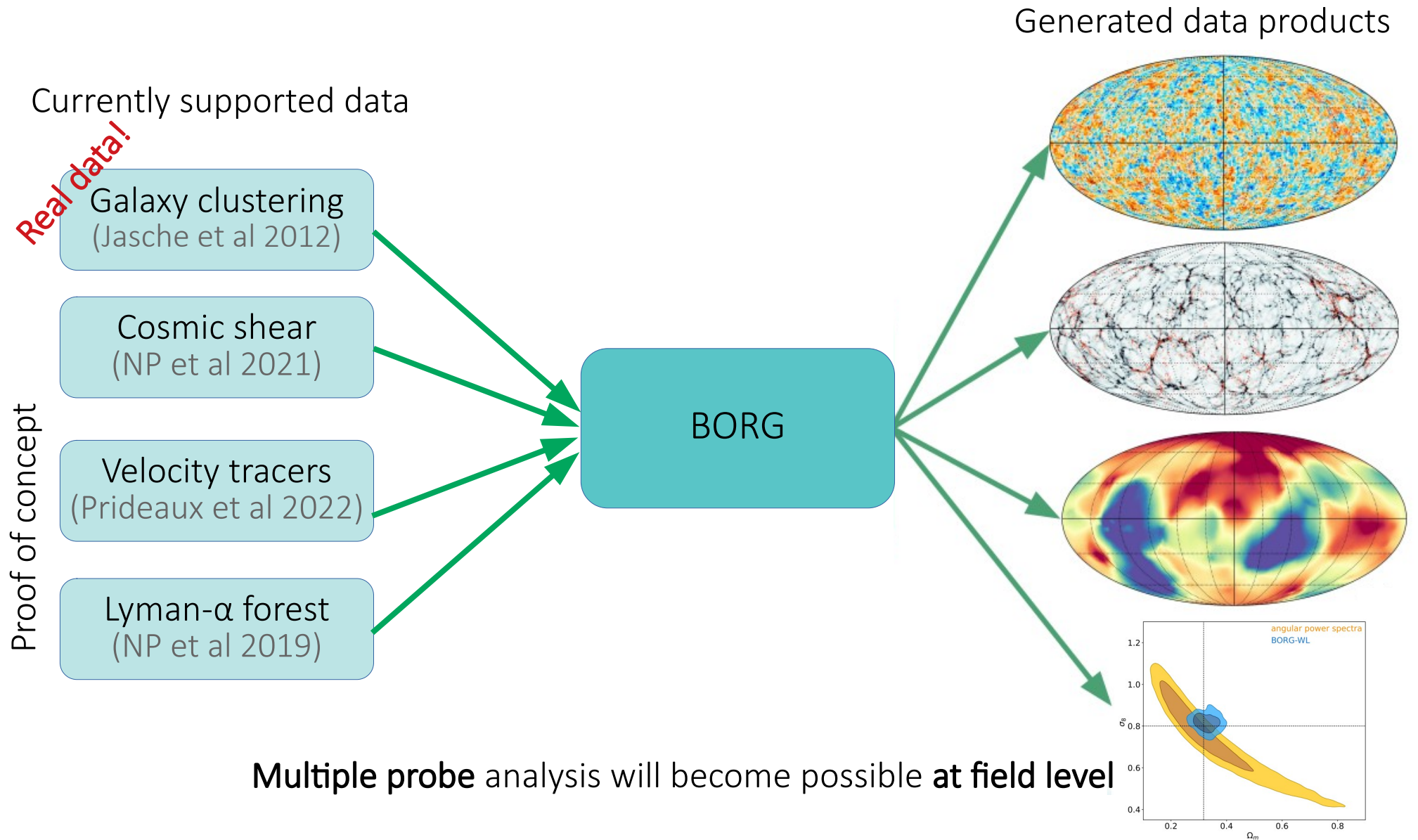
BORG

Generated data products

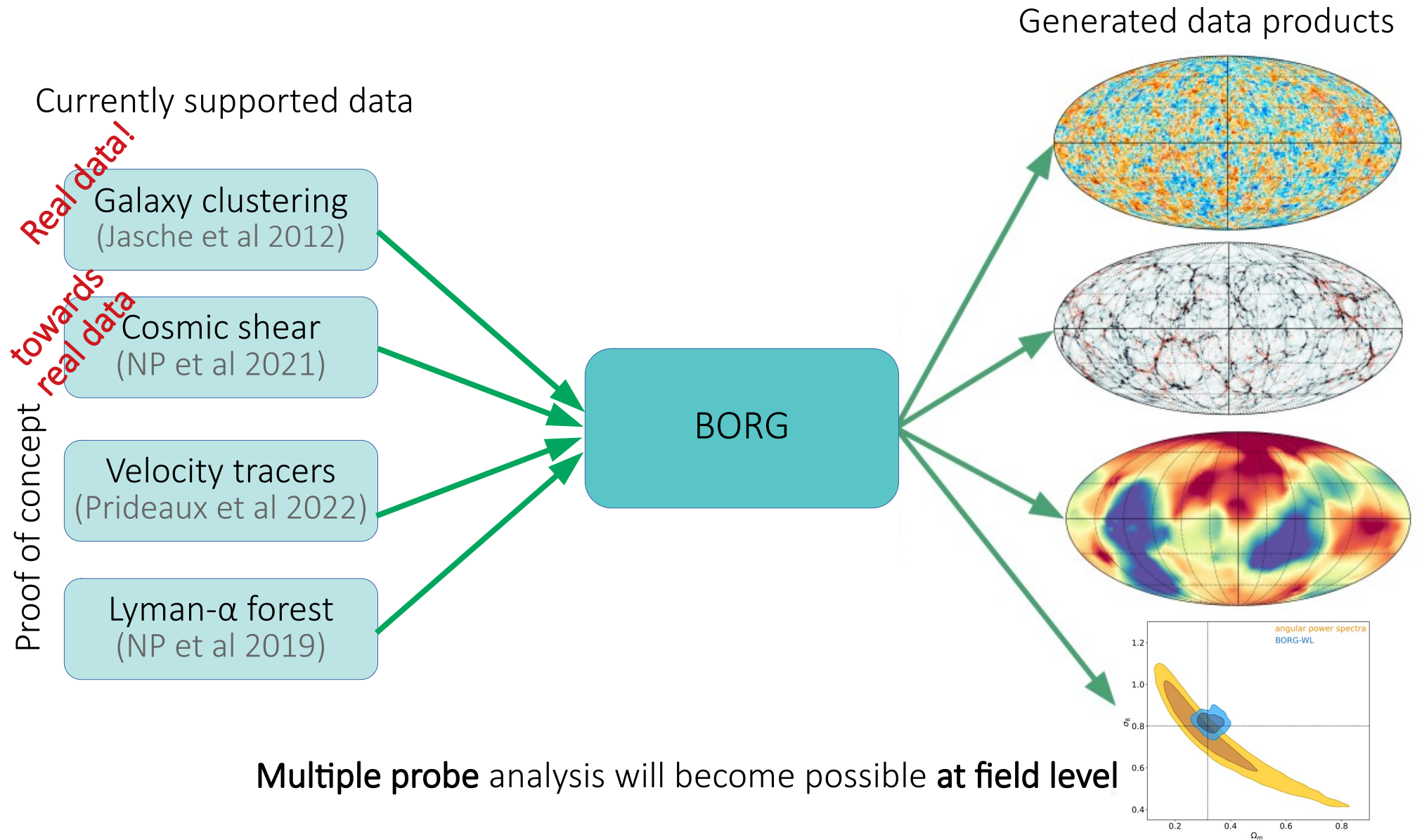


Multiple probe analysis will become possible **at field level**

The current state of BORG



The current state of BORG



The challenge

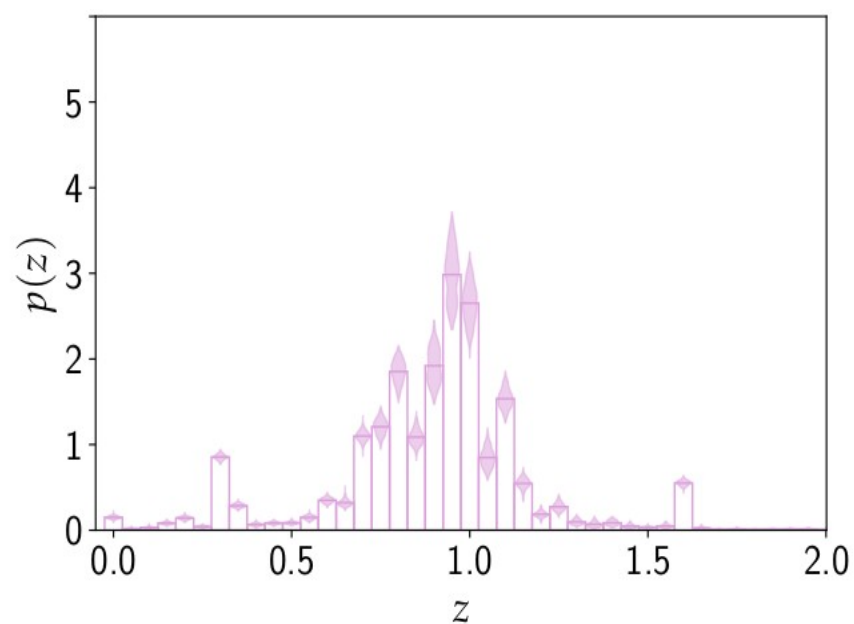
Dealing with systematics

Calibration systematics: robust $n(z)$

We need to **propagate the redshift uncertainty** to the cosmology results

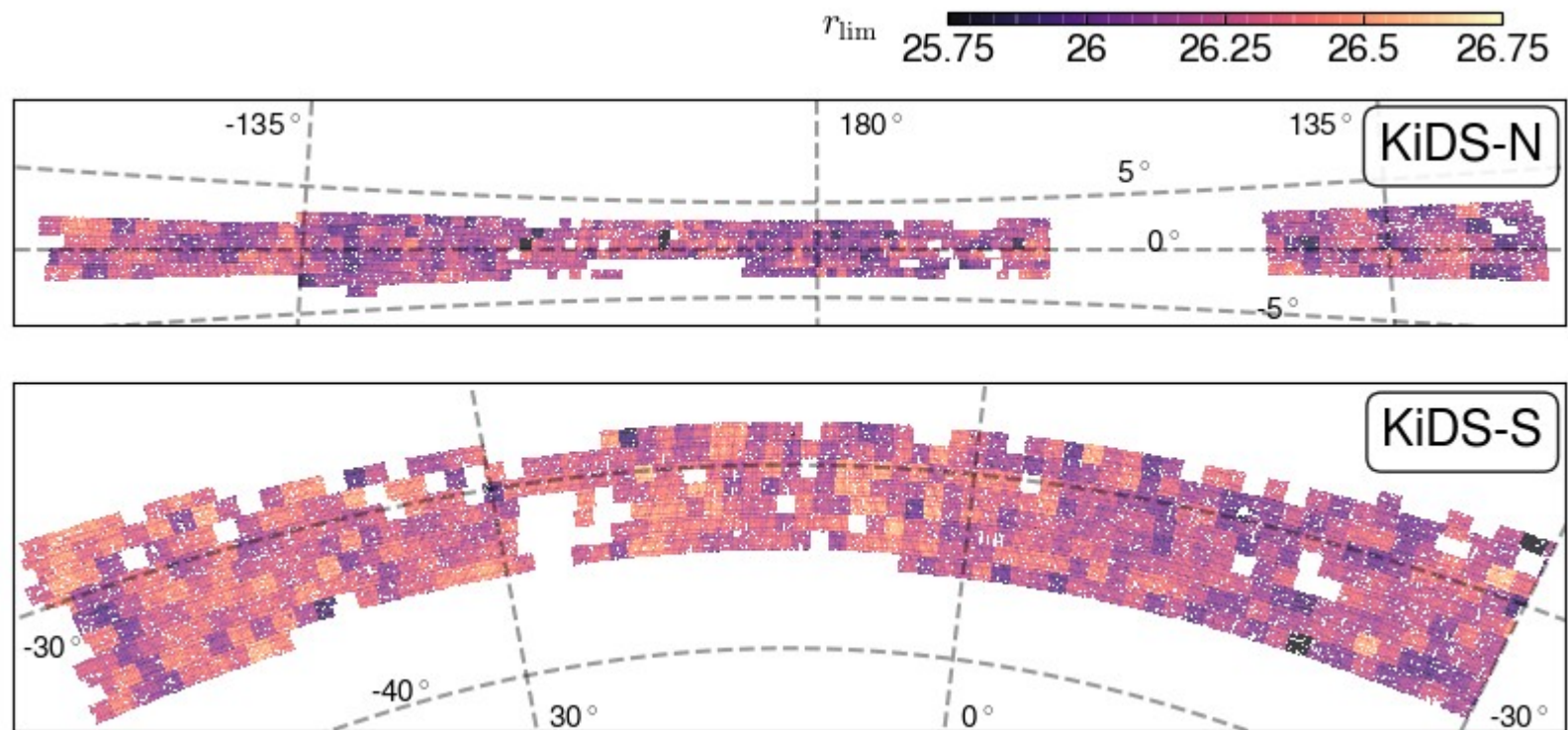
Bayesian hierarchical model to sample $n(z)$ and marginalise over redshift uncertainties

Using forward model of the photometric fluxes (Leistedt+ 2016)



Kyriacou, Heavens+ in preparation

Calibration systematics on the sky (survey depth)



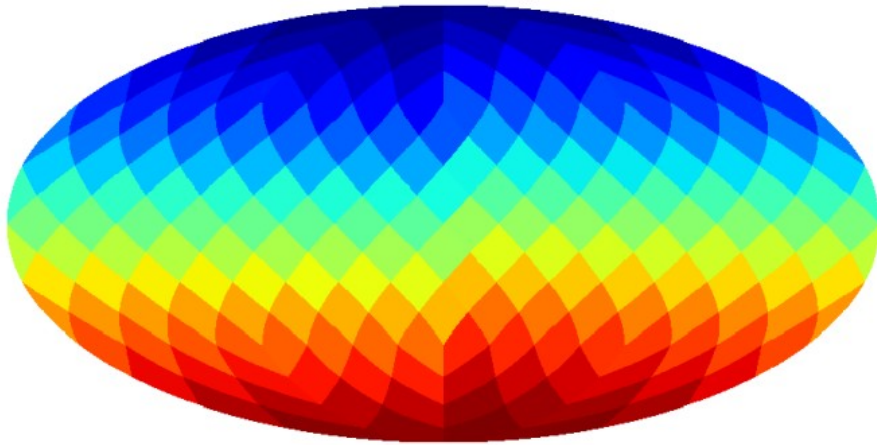
Joachimi+ 2020

- Variable depth
- Variable seeing (PSF)
- Variation in source galaxy and redshift distribution

Unknown systematics

Assuming amplitude of patch is unknown

Porqueres+ 2019
Lavaux, Jasche & Leclercq, 2019



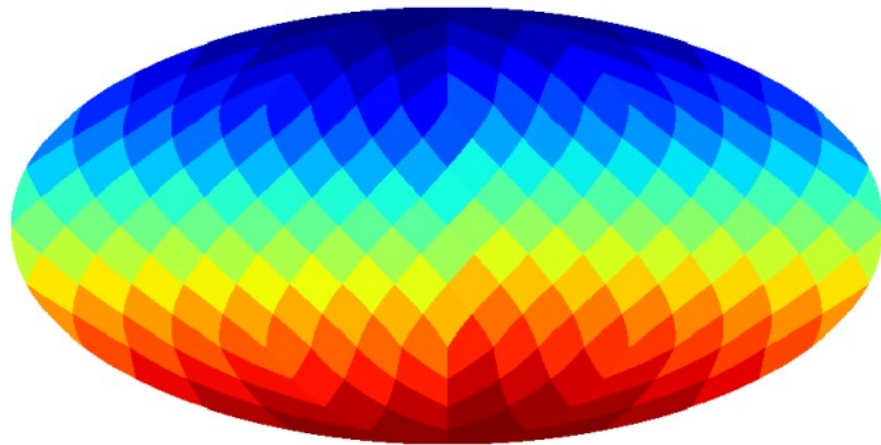
For a Poisson likelihood:

$$P(\{N\}|\{\lambda\}) \propto \prod_{\text{patch}} \prod_{i \in \text{patch}} \left(\frac{\lambda_i}{\sum_{j \in \text{patch}} \lambda_j} \right)^{N_i}$$

Unknown systematics

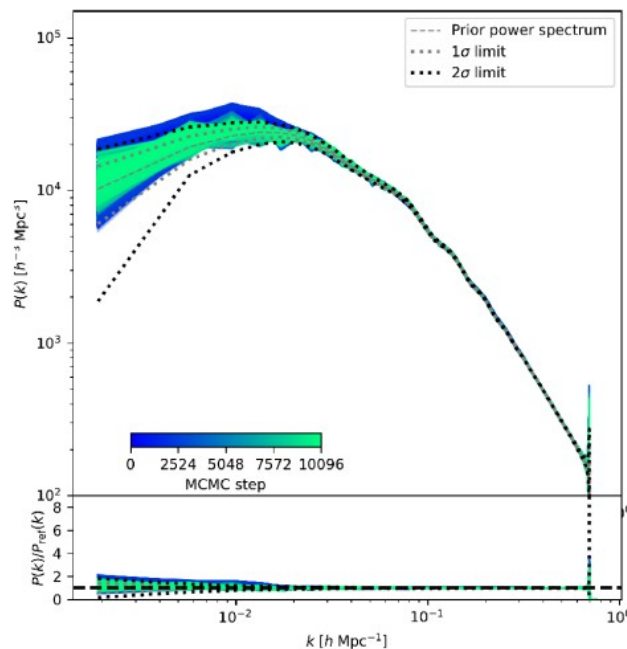
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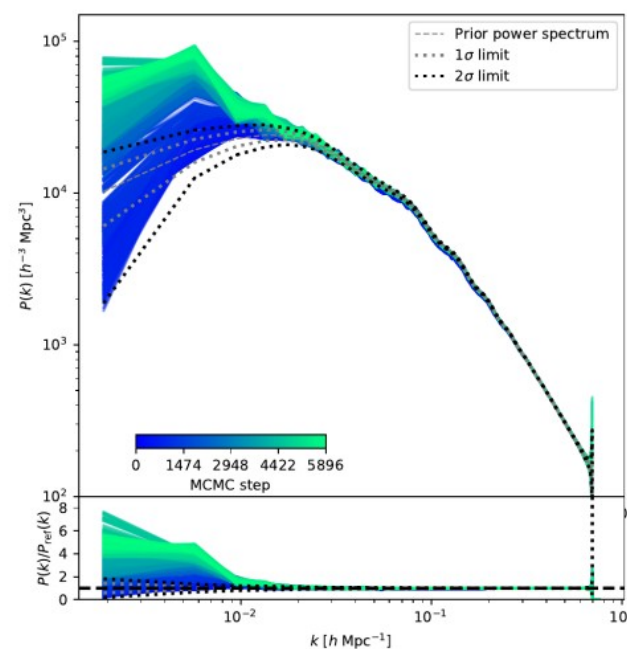


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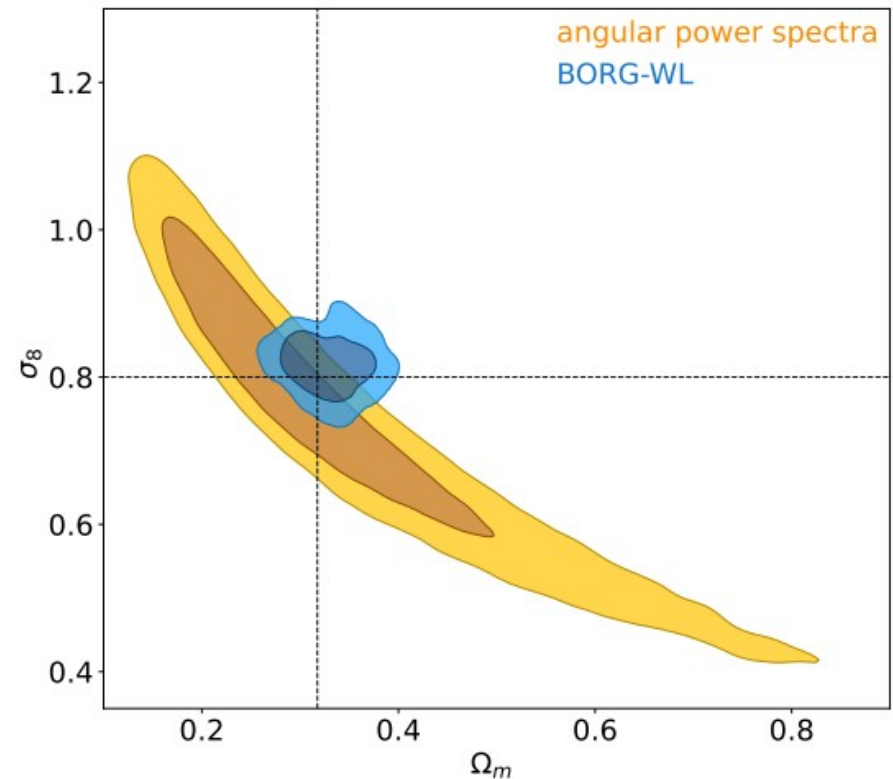
(a) Robust likelihood



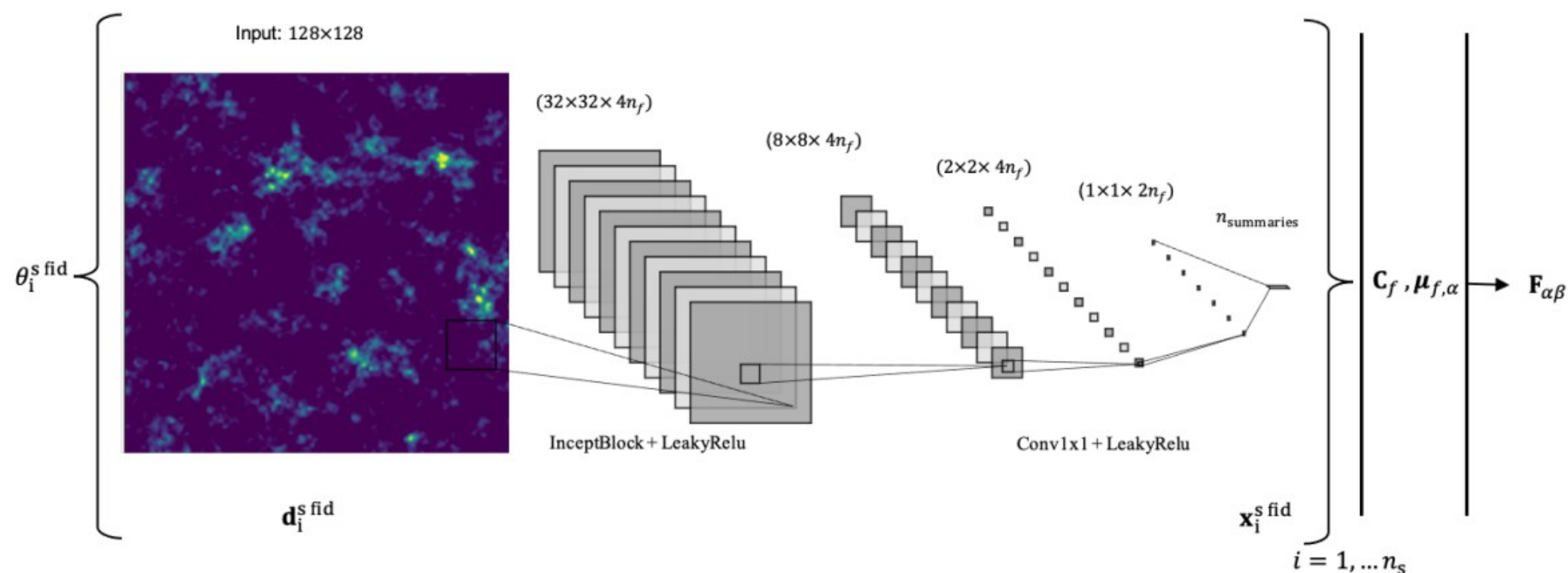
(b) Standard Poissonian likelihood

Summary

- There is more information in the data that the 2-point summary statistics do not capture.
- Field-based approach lifts degeneracy and reduces marginal error up to a factor of 5.
- What's next?
First real data analysis with BORG-WL



Can we define a summary that extracts as much information?



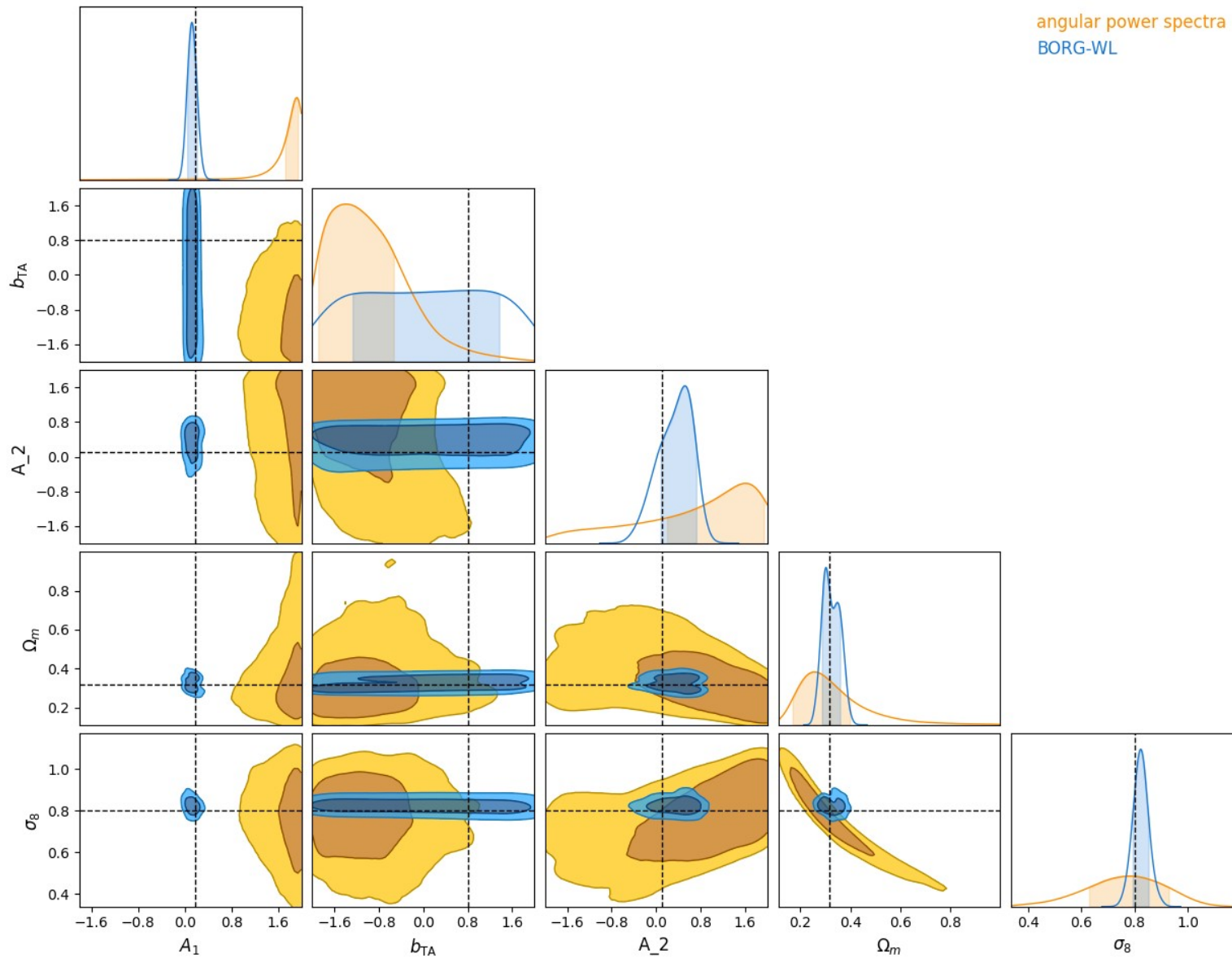
Lucas Makinen
(Imperial College)

Information Maximising Neural Networks (Charnock+2018)

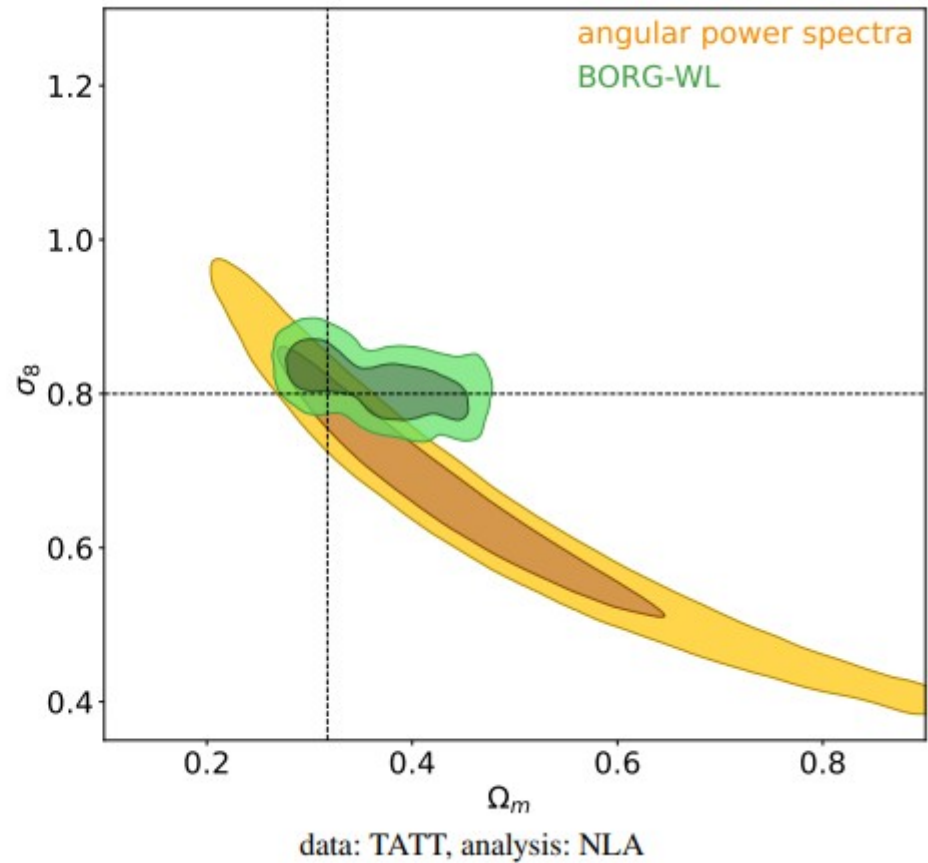
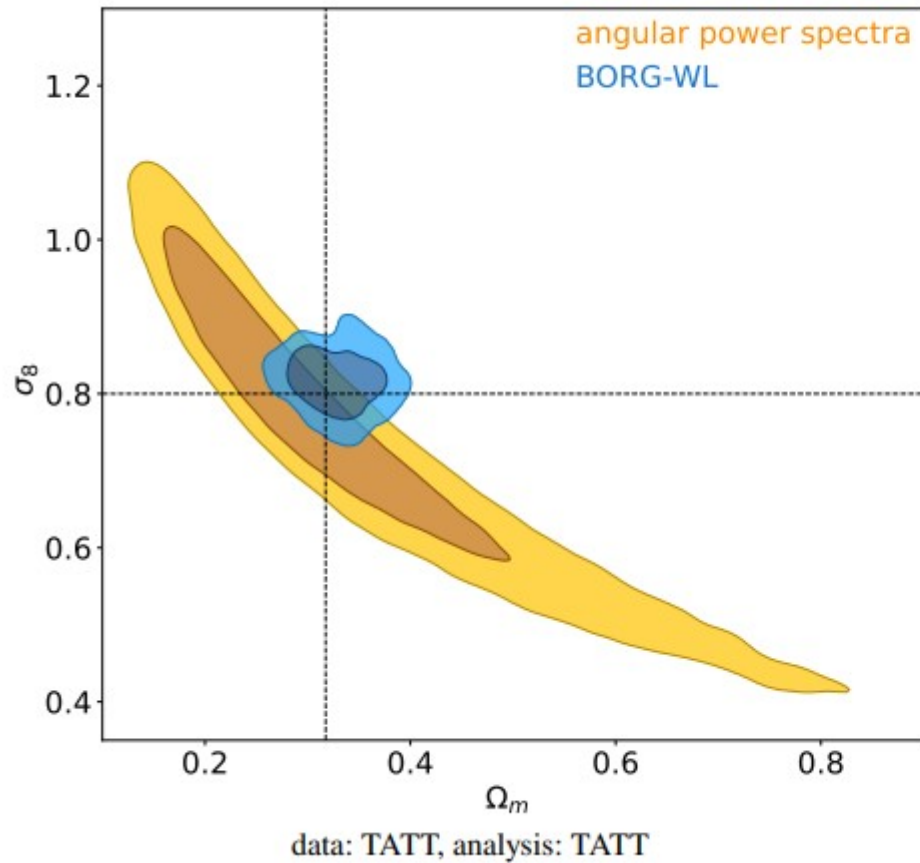
Compress data keeping Fisher matrix intact

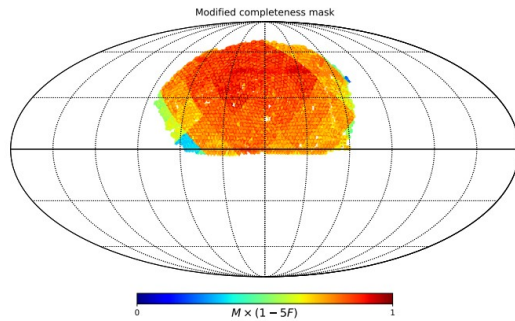
$$\mathbf{F}_{\alpha\beta}(\boldsymbol{\vartheta}) = - \left\langle \frac{\partial^2 \ln \mathcal{L}(\mathbf{d}|\boldsymbol{\vartheta})}{\partial \vartheta_\alpha \partial \vartheta_\beta} \right\rangle \bigg|_{\boldsymbol{\vartheta} = \boldsymbol{\vartheta}^{\text{fid}}}$$

Posterior distribution Cls vs BORG-WL



Model misspecification intrinsic alignments

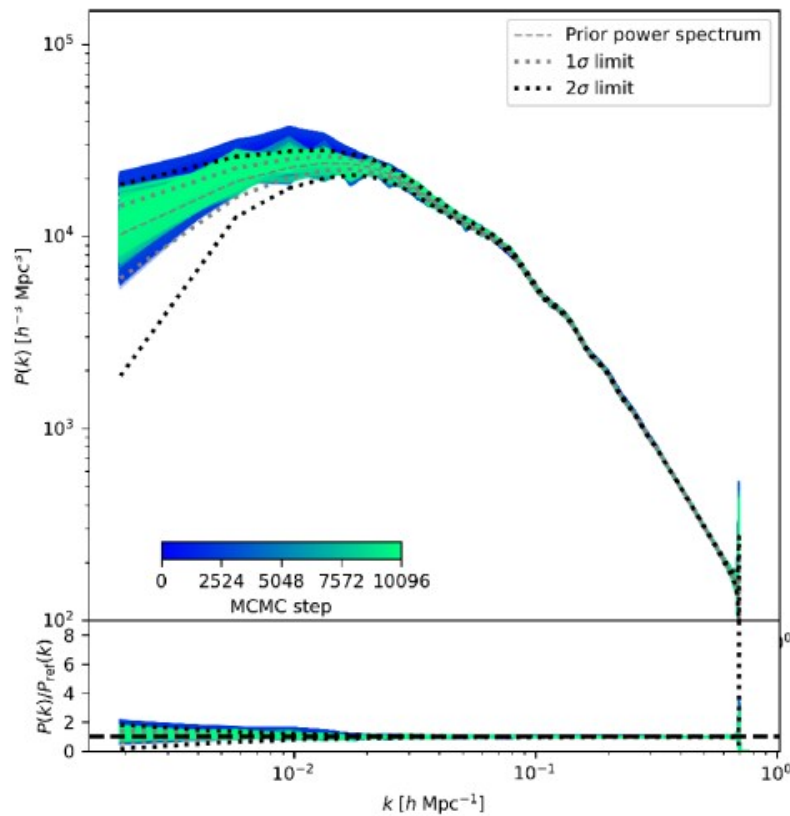




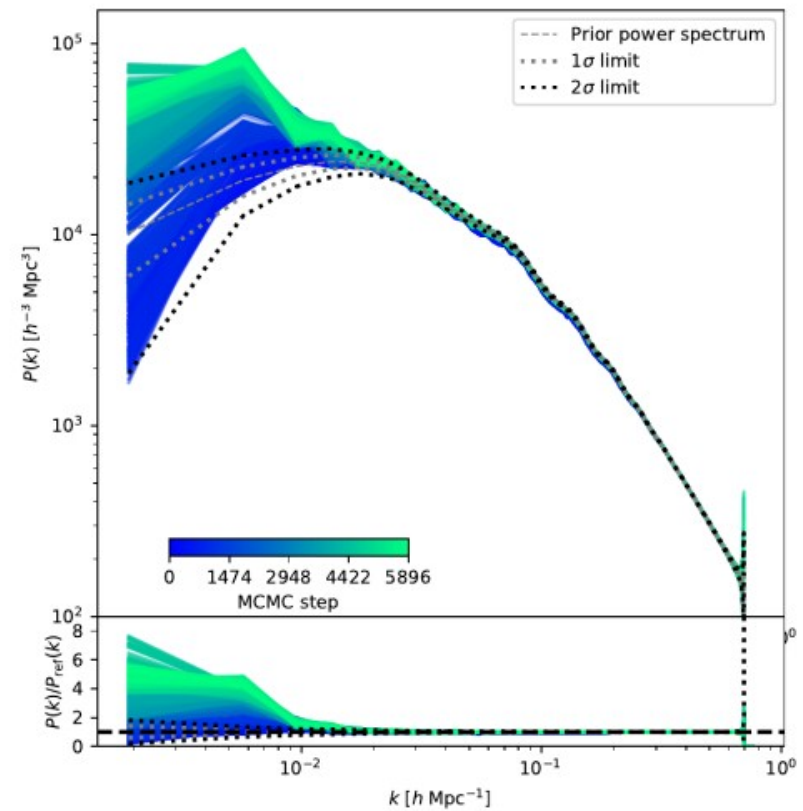
$$\lambda_c = A_c \bar{\lambda}_c$$

$$\downarrow$$

$$P(N|\lambda) = \prod_i \frac{e^{-\lambda_i} (\lambda_i)^{N_i}}{N_i!}$$



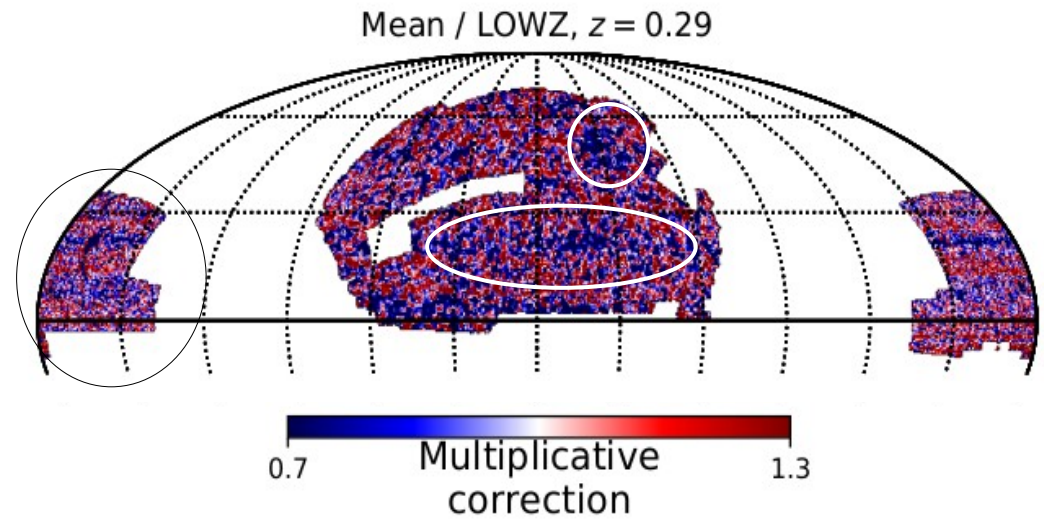
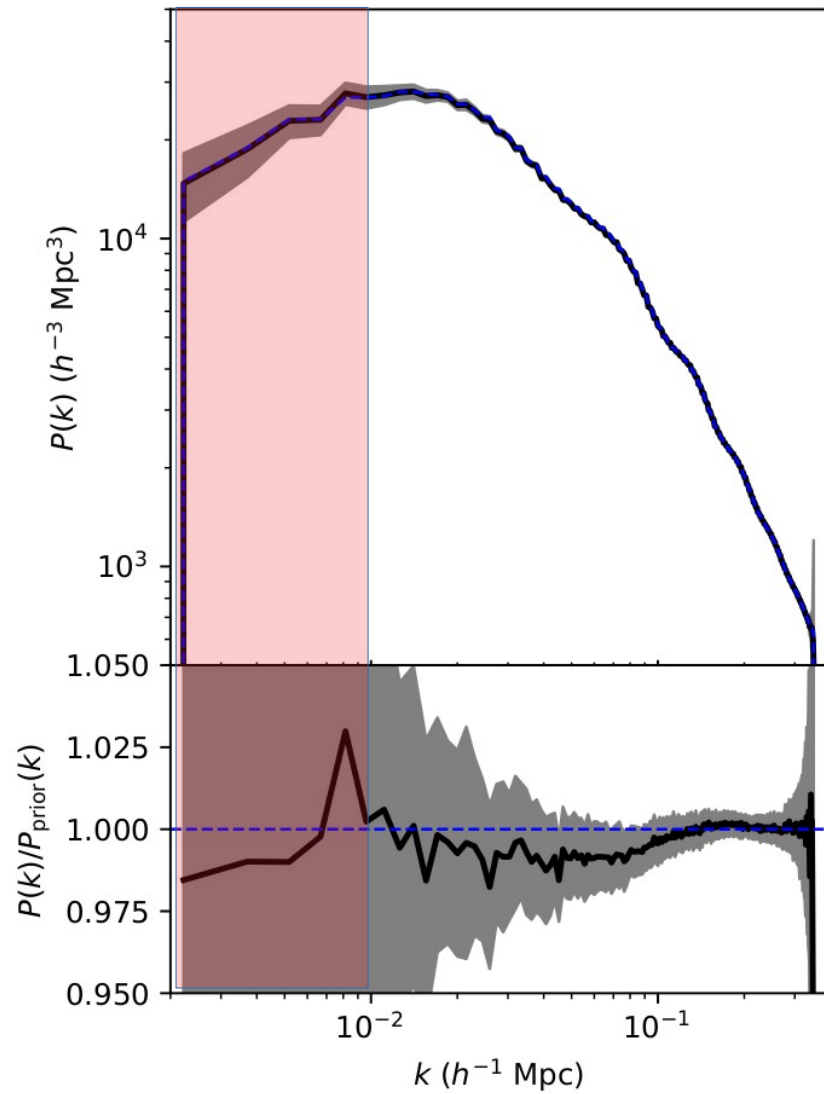
(a) Robust likelihood



(b) Standard Poissonian likelihood

Robust likelihood: SDSS-III analysis

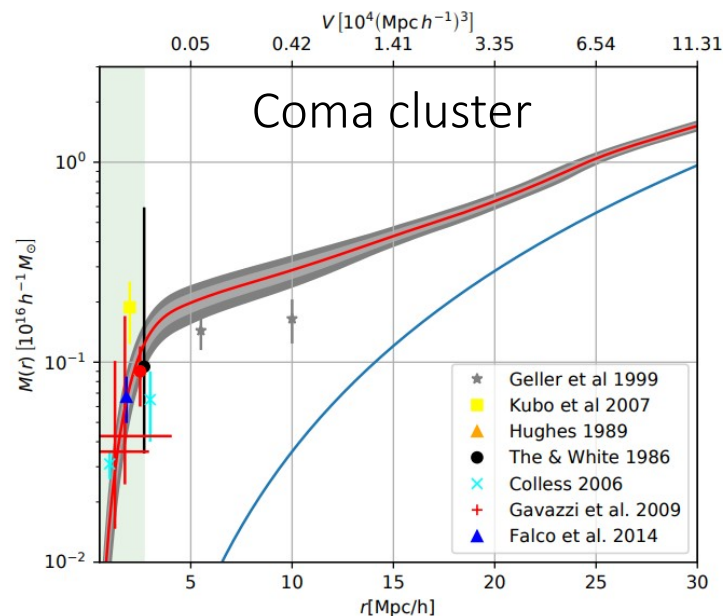
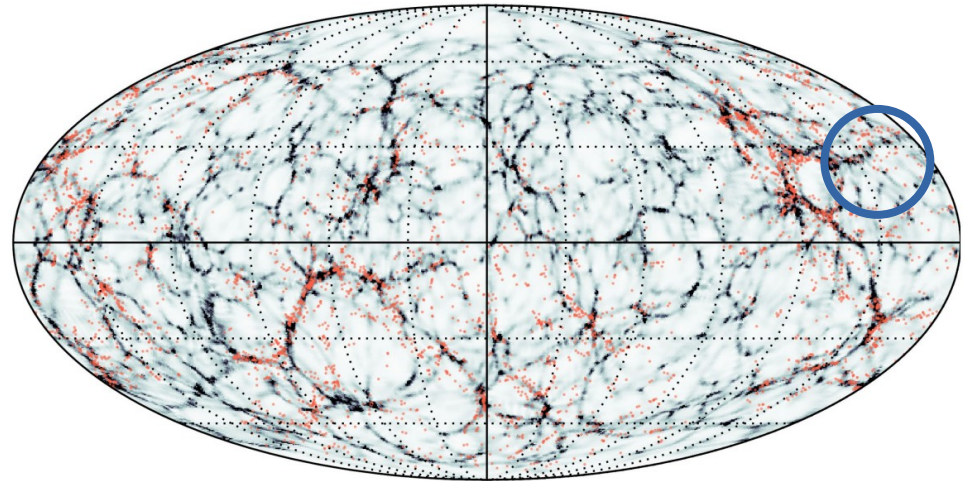
(Lavaux, Jasche, Leclercq, 2019)



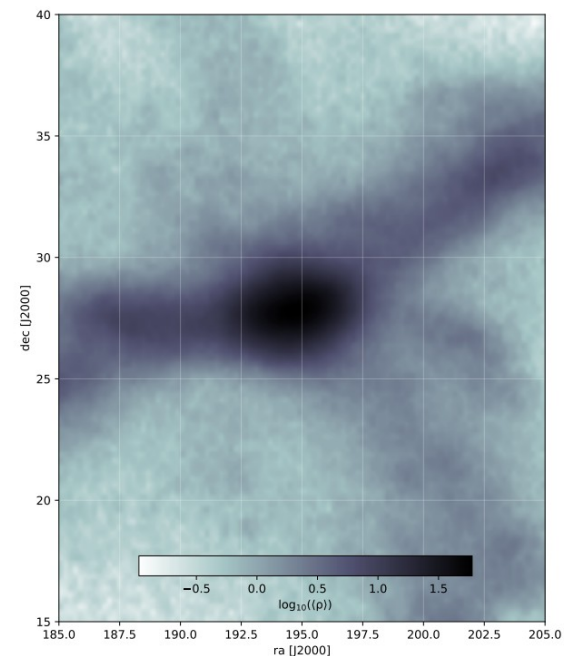
Validating the results of a real data analysis

Posterior predictive tests and cross-validation with independent measurements

- do we get the clusters we know are there?
- do we get the expected mass profiles?
- are the inferred IC compatible with CMB?



Jasche & Lavaux 2019

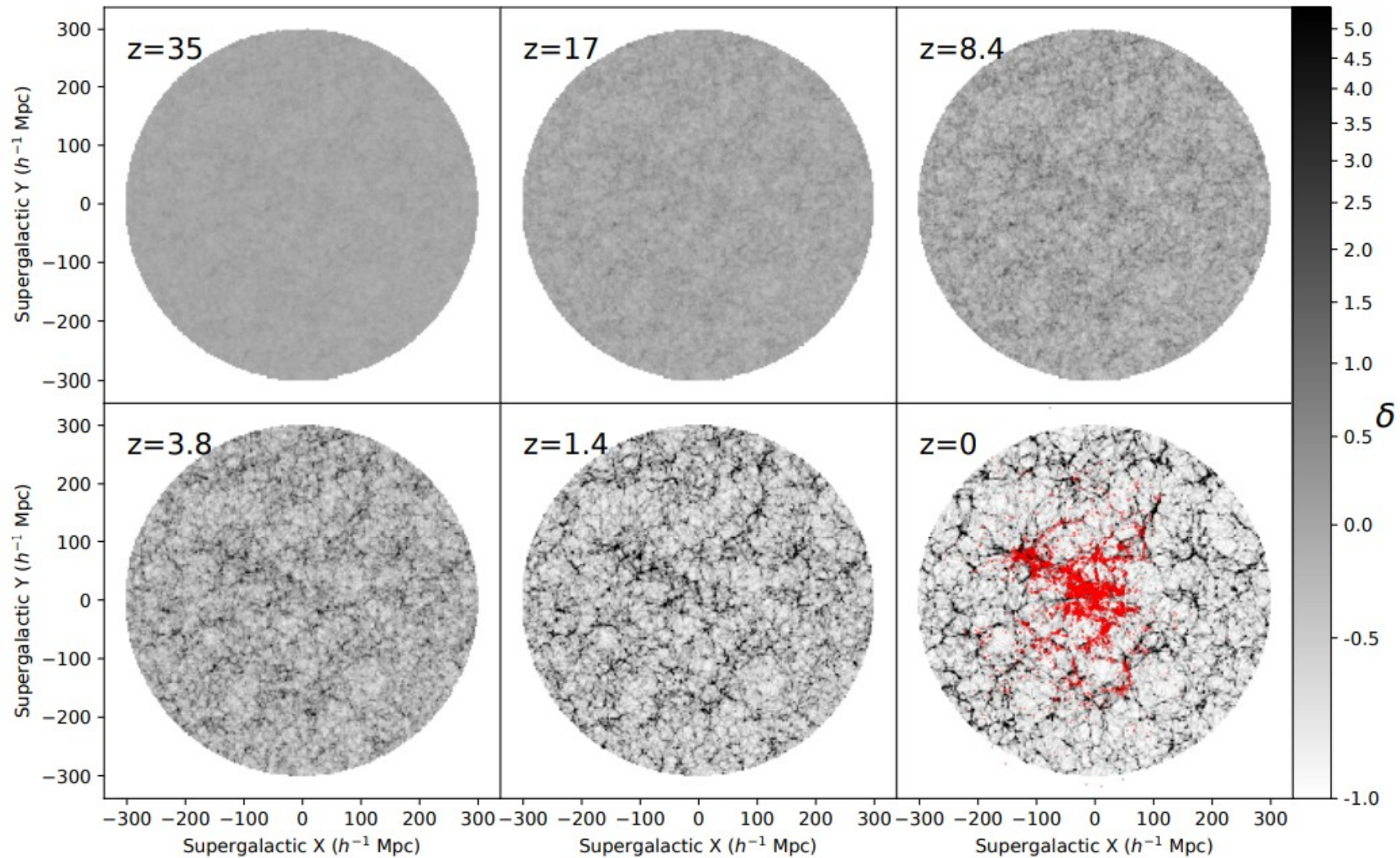


Jasche & Lavaux 2019

Natalia Porqueres

More realistic gravity model: Particle-mesh in BORG

Particle mesh is **ready** and has been **used in real data** BORG analysis (2M++)



Jasche & Lavaux 2019

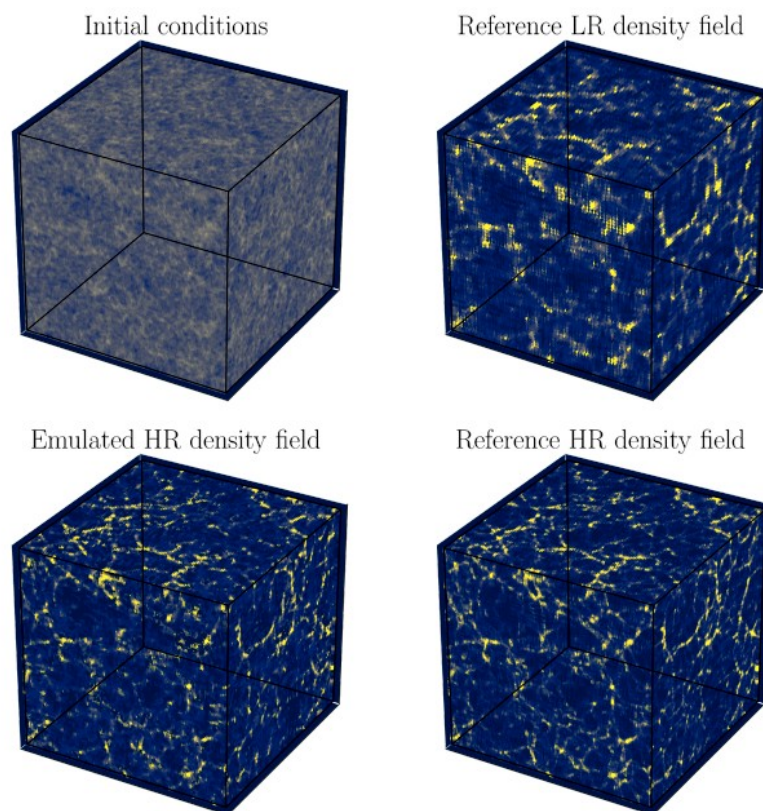
What if the models of systematics are not good enough?

Machine learning can help connecting physical models to data

Neural physical engines (Charnock+ 2019): fully Bayesian way of using NN in MCMC inference

- encoding symmetries to reduce dimensionality
- inferring NN parameters from data. No training data!

An example in BORG: Emulating high resolution N-body



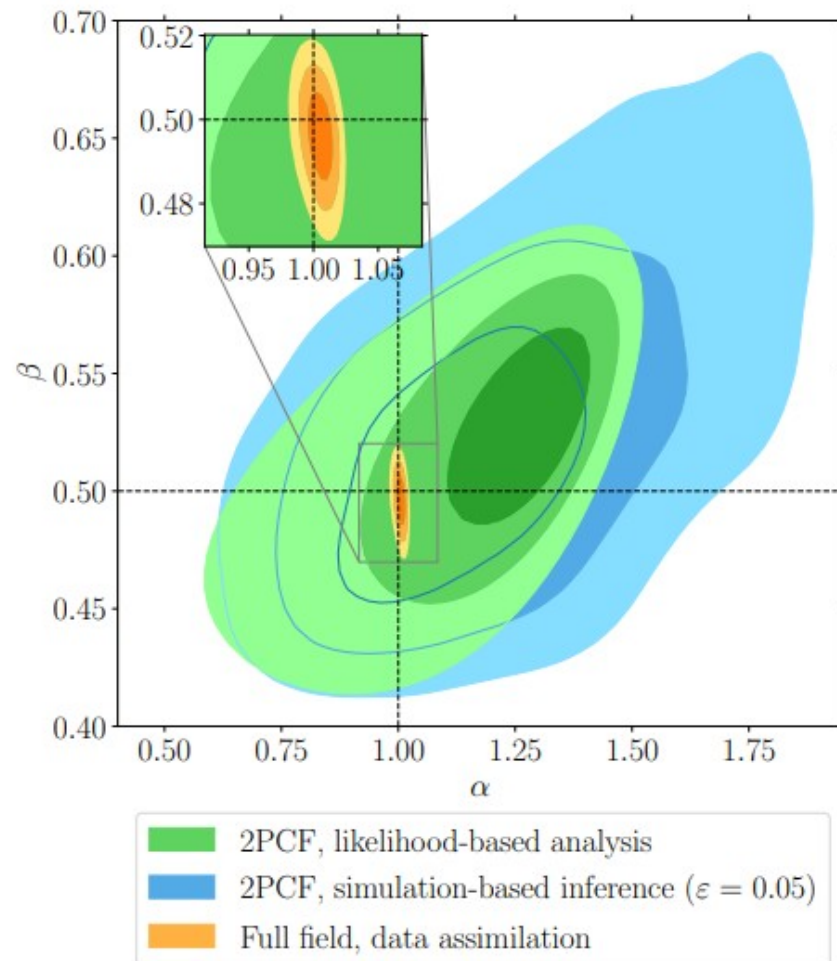
Charnock+ 2019

Table of cosmological constraints

	Power spectra	BORG-WL	
Ω_m	$0.3^{+0.5}_{-0.2}$	$0.34^{+0.07}_{-0.05}$	Factor 5
σ_8	$0.6^{+0.4}_{-0.3}$	$0.79^{+0.11}_{-0.11}$	Factor 3
S_8	$0.80^{+0.15}_{-0.10}$	$0.83^{+0.10}_{-0.10}$	Factor 1.2

Where does the information come from?

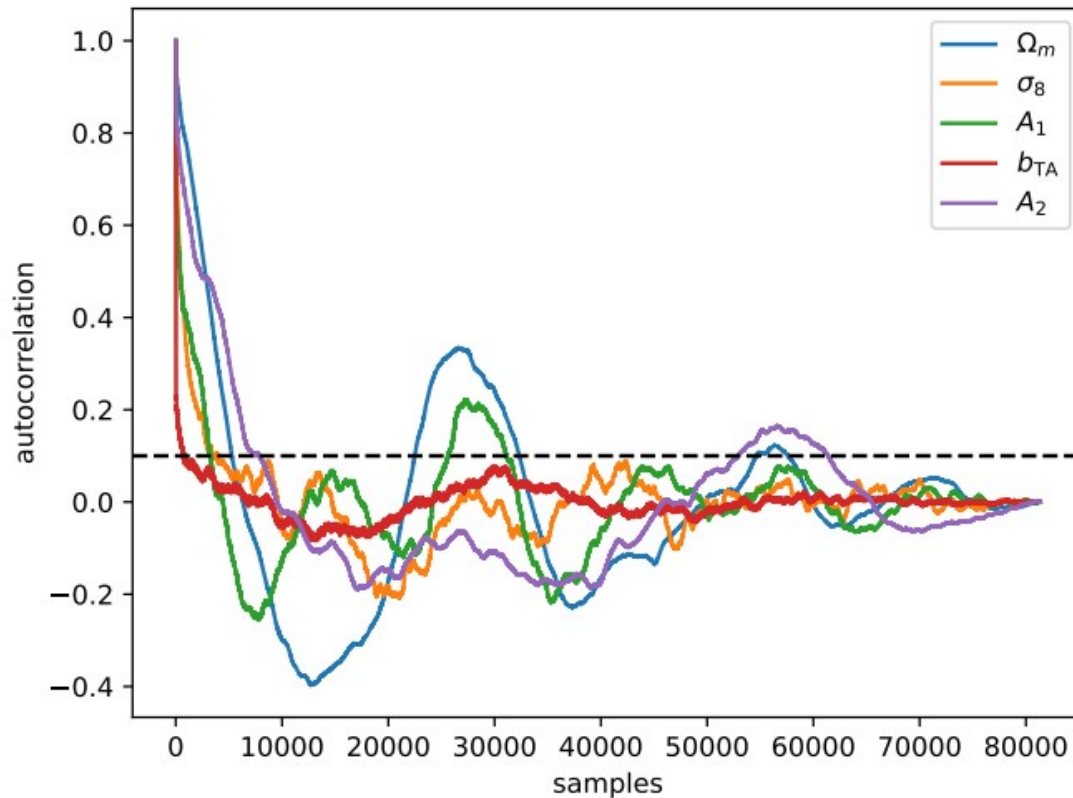
For a log-normal field:



Field-based approach: **more precise** for even nearly Gaussian fields.

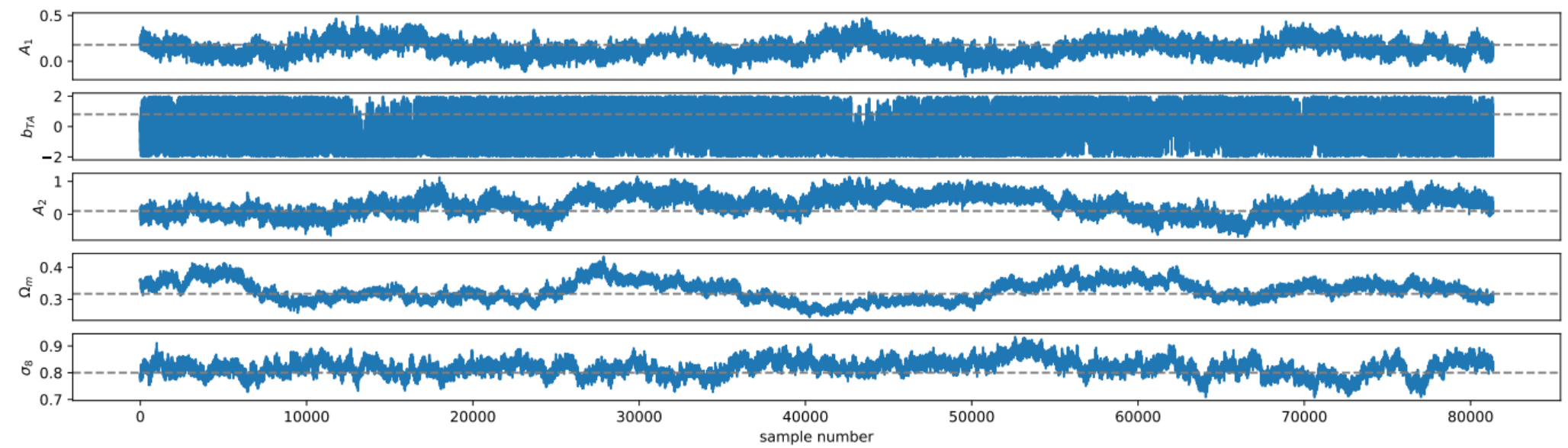
Leclercq & Heavens (2021)

Convergence test and correlation length

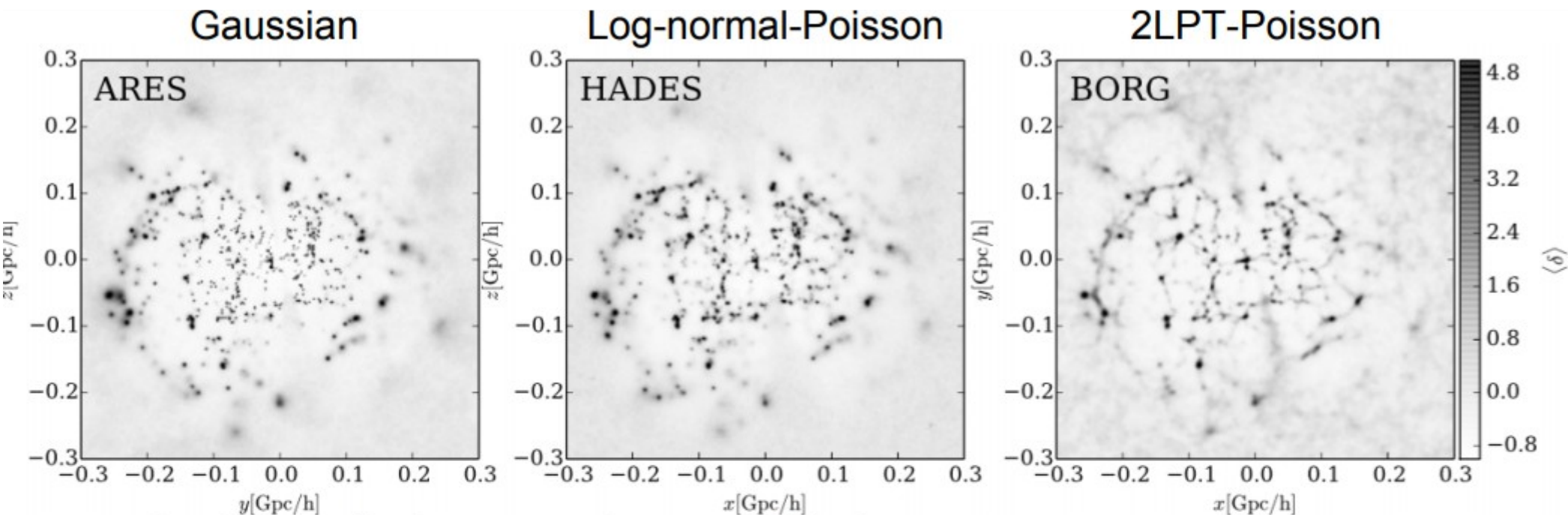


Gelman-Rubin test < 1.04 for all cosmological parameters

Trace plots



Comparison between field-based approaches (J. Jasche)



a.k.a: Wiener-filtering
Zaroubi et al. 1994
Erdogdu et al. 2004
Kitaura & Ensslin 2008
Grannet et al. 2015

log-normal-filtering
Kitaura 2010
Jasche & Kitaura 2010

Jasche&Wandelt 2012

Which scheme performs best?

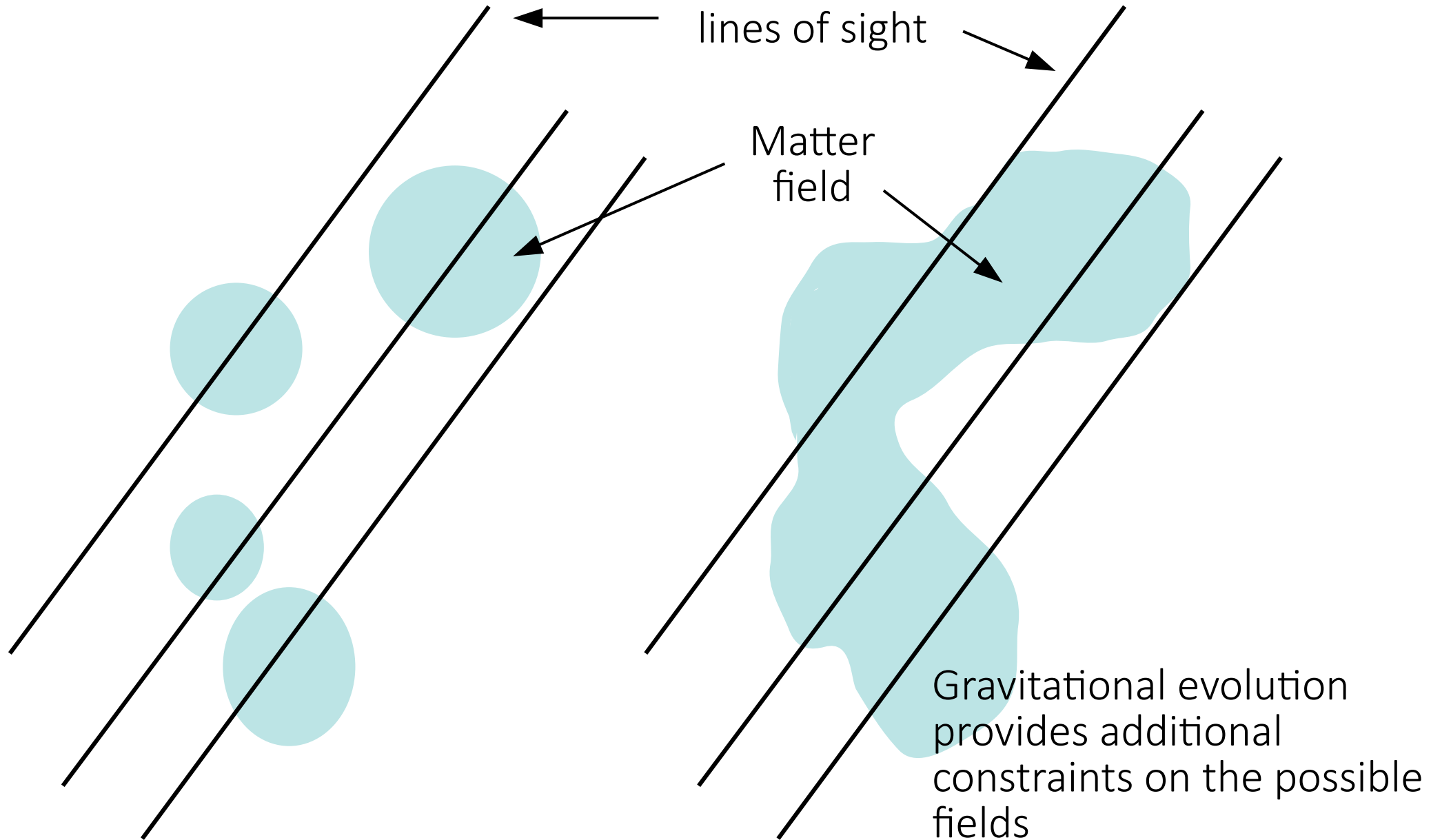
Ask the data!

$$A_{ij} = \ln(\mathcal{P}(d|\delta_i)) - \ln(\mathcal{P}(d|\delta_j))$$

	ARES	HADES	BORG
ARES	0	-219580.31	-383482.25
HADES	219580.31	0	-163901.94
BORG	383482.25	163901.94	0.

Wiener filter

Forward modeling



Hamiltonian Monte Carlo

Define potential $\psi = -\ln(P(x))$

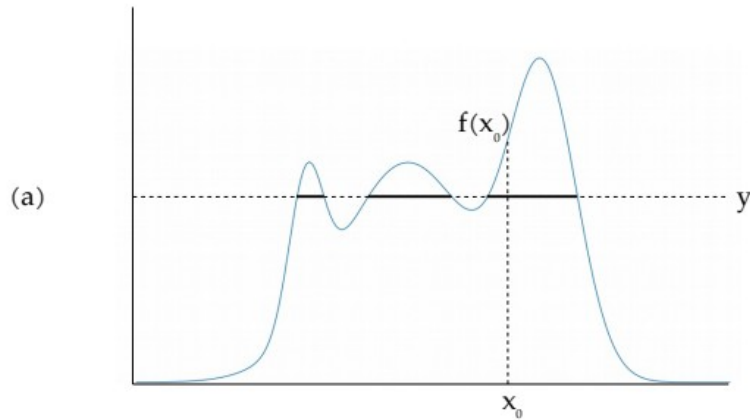
Define Hamiltonian $H = \frac{1}{2}\mathbf{p}^T \mathbf{M}^{-1} \mathbf{p} + \psi(x)$

Use mechanics:

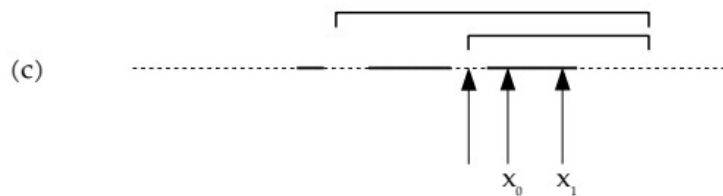
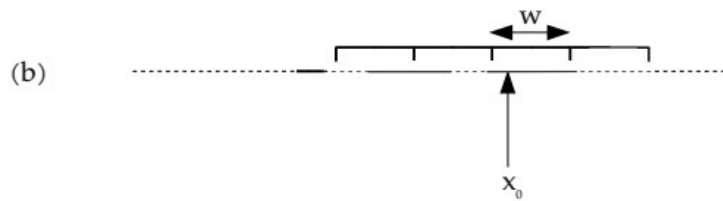
$$(x, p) \longrightarrow \begin{array}{l} \frac{d\mathbf{X}}{dt} = \frac{\partial H}{\partial \mathbf{p}} = \mathbf{M}^{-1} \mathbf{p} \\ \frac{d\mathbf{p}}{dt} = -\frac{\partial H}{\partial \mathbf{X}} = -\frac{\partial \psi(x)}{\partial \mathbf{X}} \end{array} \longrightarrow (x', p')$$

Randomise momentum and accept $\alpha = \min[1, e^{-(H-H')}] = 1$

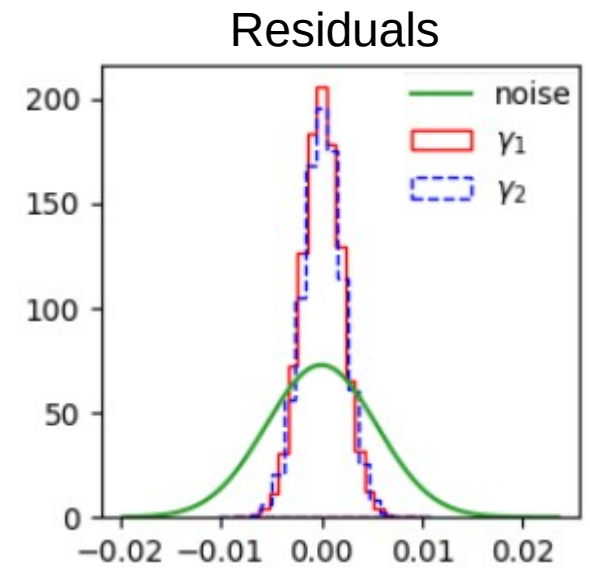
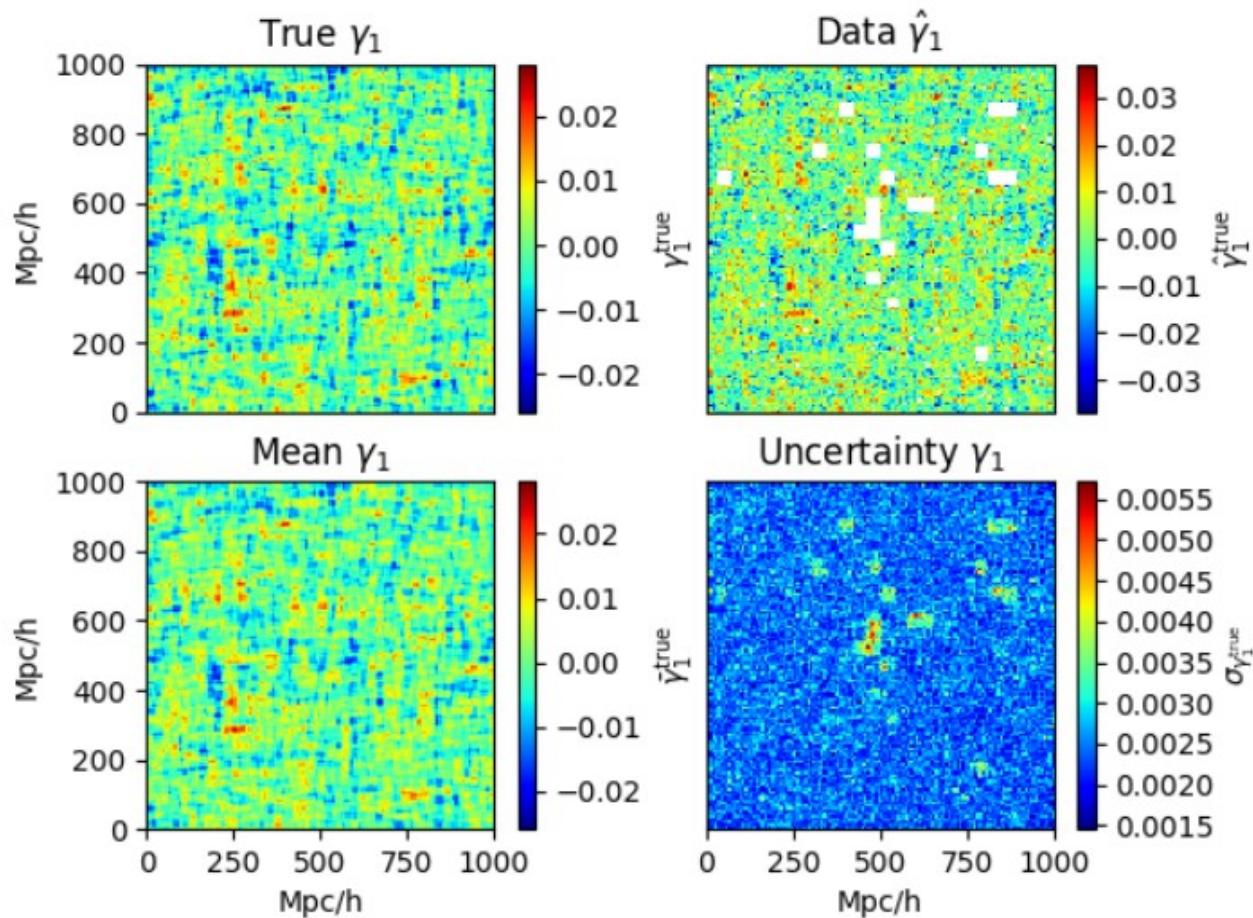
Slice sampler



MCMC algorithm

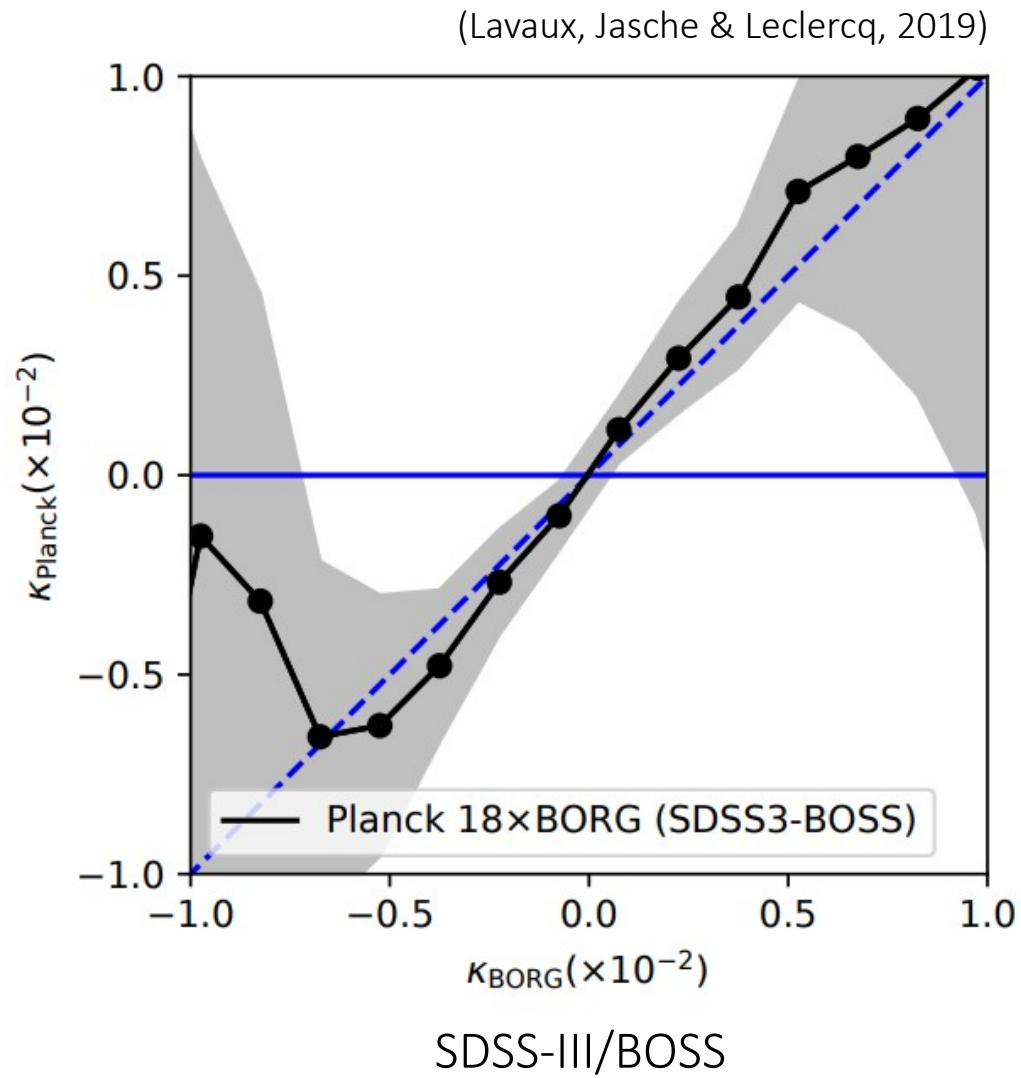


Test with mask



Inferred quantities
explain data to sub-noise
level

CMB lensing



Sampling efficiently in a high-dimensional space

Hamiltonian Monte Carlo
- density field

Slice sampler
- cosmological parameters
- nuisance parameters
- systematics

Define potential $\psi = -\ln(P(x))$

Hamiltonian $H = \frac{1}{2}\mathbf{p}^T\mathbf{M}^{-1}\mathbf{p} + \psi(x)$

Use mechanics to solve a statistical problem:

$$\frac{d\mathbf{X}}{dt} = \frac{\partial H}{\partial \mathbf{p}} = \mathbf{M}^{-1}\mathbf{p}$$
$$\frac{d\mathbf{p}}{dt} = -\frac{\partial H}{\partial \mathbf{X}} = -\frac{\partial \psi(x)}{\partial \mathbf{X}}$$

Addresses curse of dimensionality by
- exploiting information in gradients
- using conserved quantities

The challenge for upcoming surveys

Upcoming surveys will provide large volumes of **high-quality data**.

→ unprecedented statistical power.

→ great potential for discoveries.

But...

→ existing methods are reaching their limits.

→ good control of systematics becomes paramount.

We need **new data analysis techniques** to fully realise the potential of these surveys.

- Higher-order statistics: what are the sampling distributions? And covariance matrix?
- Field-based approach without data compression of the pixelised shear.